



2010-09-21



5011692102-EPC2

# DTE10P Series Temperature Controller Instruction Sheet

Thank you very much for choosing Delta DTE series temperature controller. Please read this instruction sheet carefully before using your DTE to ensure proper operation. Keep this instruction sheet handy for quick reference.

## ■ Precaution



### DANGER! Caution! Electric Shock!

DTE is an OPEN-TYPE device and therefore should be installed in an enclosure free of airborne dust, humidity, electric shock and vibration. The enclosure should prevent non-maintenance staff from operating the device (e.g. key or specific tools are required for opening the enclosure) in case danger and damage on the device may occur.



### WARNING!

1. Prevent dust or metallic debris from falling into the device and cause malfunctions. DO NOT modify or uninstall the circuit board of DTE without being permitted. DO NOT use empty terminals.
2. Keep away from high-voltage and high-frequency environment during the installation in case of interference. Prevent using the device in premises which contain:
  - (a) dust or corrosive gas; (b) high humidity and high radiation; (c) shock and vibration.
3. The power has to be switched off when wiring or changing the temperature sensor.
4. When installing the circuit board of the accessory, please make sure the power of the main unit is switched off and insert the accessory into the correct slot on the main unit.
5. Make sure to use compensation wire which matches the thermocouple or platinum resistance when extending or connecting the thermocouple or platinum resistance.
6. Keep the wire as short as possible when wiring a sensor to the controller. Separate the power cable and load wire in order to prevent interference and induced noise.
7. Make sure the power cables and signal device are installed correctly before switching on the power; otherwise serious damage may occur.
8. DO NOT touch the terminal or repair the device when the power is on; otherwise an electric shock may occur.
9. Please wait for 1 minute after the power is switched off to allow the capacitor to discharge and DO NOT touch the internal wiring within this period.
10. DO NOT touch the internal terminal when DTE is either switched on or off in case you may damage the circuit.
11. Please place DTE with other heating objects (e.g. power supply) within proper distance while installing DTE.

## ■ Ordering Information

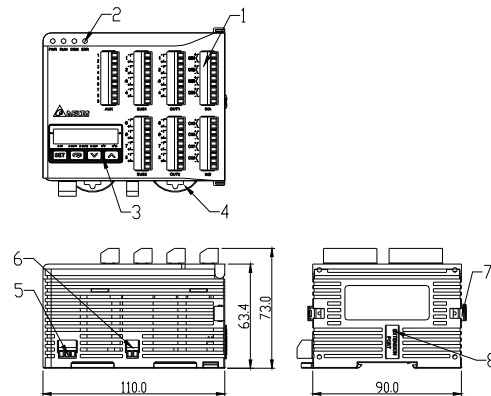
DTE 1 2 3 - 4

Series name	DTE: Delta E series temperature controller		
<span style="border: 1px solid black; padding: 0 2px;">1</span> Device type	1: main unit	2: accessory	
<span style="border: 1px solid black; padding: 0 2px;">2</span> <span style="border: 1px solid black; padding: 0 2px;">3</span> - <span style="border: 1px solid black; padding: 0 2px;">4</span>	OT: 4-channel TC OP: 3-channel PT	OT: 4-channel TC OV: 4 channels of voltage pulse output OC: 4 channels of linear current output OR: 4 channels of relay output OL: 4 channels of linear voltage output CT: 4 channels of current transformer sensors DS: Display and setup module	OP: 3-channel PT OD: 8-channel EVENT input

## ■ Specifications

Power input	24 VDC, isolated switching power supply
Voltage range	90 to 110% rated voltage
Power consumption	Max. 10W + 3W × number of DTC2000 controllers connected in parallel (Max. 7)
Input sensor	Thermocouple: K, J, T, E, N, R, S, B, L, U, TXK
	Platinum resistance: Pt100, JPt100, Ni120, Cu50
Sampling cycle	Thermocouple or platinum resistance: 1.0 second/all input
Control method	PID, PID programmable, manual, ON/OFF
Output accessories (optional)	Relay output: SPST, Max. 250 VAC load, 3 A resistive load
	Voltage pulse output: 12 VDC, Max. 40 mA current output
	Current output: DC 4 to 20 mA output (resistive load < 500Ω); for OUT1 and OUT2 only
Output functions (optional)	Analog voltage output: 0 to 10 V (resistive load > 1,000Ω); for OUT1 and OUT2 only
	Control output, alarm output or proportional output (proportional output is only applicable in the model with linear voltage and current output for OUT1, OUT2)
Alarm modes (optional)	13 alarm modes available
Communication	RS-485 digital communication; supports baud rate 2,400 to 115,200 bps
Communication protocol	Supports Modbus ASCII/RTU
Extension port	The extension port transmits 24V power supply and communication signals to extension module DTC2000.
Vibration resistance	10 ~ 55Hz 10m/s <sup>2</sup> 3 axes 10mins
Shock resistance	Max. 300m/s <sup>2</sup> 3 axes 6 directions, 3 times each
Ambient temperature	0 to +50°C
Storage temperature	-20 to +65°C
Operation altitude	< 2,000m
Ambient humidity	35 to 85% RH (non-condensing)
Pollution degree	2

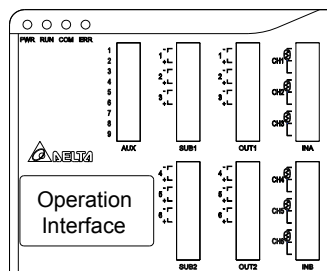
## ■ Product Profile & Outline



### DTE10P

- |   |                              |
|---|------------------------------|
| 1 | I/O terminals                |
| 2 | Status LED                   |
| 3 | Display and setup unit       |
| 4 | DIN rail clip                |
| 5 | Power input port             |
| 6 | RS-485 communication port    |
| 7 | Extension module fixing clip |
| 8 | Extension port               |

## ■ Panel Layout



## ■ Input

The standard DTE main unit is attached with 3 channels of inputs. You can purchase additional DTE20P to expand the number of input channels. DTE supports maximum 6 channels of inputs which belong to group INA and group INB. Each group possesses 3 input channels. DTE series supports the following input sensors:

Input Sensor Type	Register Value	Range
For DTE10P / DTE20P		
Temperature measurement resistance (Cu50)	14	-50 ~ 150°C
Temperature measurement resistance (Ni120)	13	-80 ~ 300°C
Platinum resistance (Pt100)	12	-200 ~ 850°C
Platinum resistance (JPt100)	11	-20 ~ 400°C
For DTE10T / DTE20T		
Thermocouple TXK type	10	-200 ~ 800°C
Thermocouple U type	9	-200 ~ 500°C
Thermocouple L type	8	-200 ~ 850°C
Thermocouple B type	7	100 ~ 1,800°C
Thermocouple S type	6	0 ~ 1,700°C
Thermocouple R type	5	0 ~ 1,700°C
Thermocouple N type	4	-200 ~ 1,300°C
Thermocouple E type	3	0 ~ 600°C
Thermocouple T type	2	-200 ~ 400°C
Thermocouple J type	1	-100 ~ 1,200°C
Thermocouple K type	0	-200 ~ 1,300°C

Note: The default setting in DTE10P is "Pt100".

Communication address: Input sensor types at H10A0 ~ H10A5; input upper limits at H1010 ~ H1015; input lower limits at H1018 ~ H101D.

## ■ Output

DTE supports maximum 12 channels of outputs, belonging to output groups OUT1, OUT2, SUB1 and SUB2, each group with 3 channels. See the explanations below for how input channels correspond to output groups.

- Without group INB (3 channels of input): Every channel corresponds to 2 groups of output and 2 groups of alarms. OUT1 and SUB1 are for control output, and OUT2 and SUB2 are fixed for alarm output.
- With group INB (6 channels of input): Every channel is paired with 2 groups of outputs. OUT1 and OUT2 are used for control output or proportional output of CH1 ~ CH6. SUB1 and SUB2 are used for control output or alarm output.

See Table 1 for the relations between input and output.

Output Group	3 channels of input	6 channels of input	
	INA (CH1 ~ CH3)	INA (CH1 ~ CH3)	INB (CH4 ~ CH6)
OUT1	Main control output or proportional output	Main control output or proportional output	No corresponding output
OUT2	Alarm 1 output	No corresponding output	Main control output or proportional output
SUB1	Control output	Control output or alarm 1 output	No corresponding output
SUB2	Alarm 2 output	No corresponding output	Control output or alarm 1 output

Table 1

Note: SUB1 and SUB2 do not support DTE20L and DTE20C. Please install the optional output modules you purchase into the correct slot.

### ● Communication Address of Output & How to Set up Parameters

See Table 2 for the communication addresses of output and Table 3 for the definition of the value in the address.

	INA			INB		
	CH1	CH2	CH3	CH4	CH5	CH6
OUT1, OUT2	H10A8	H10A9	H10AA	H10AB	H10AC	H10AD
SUB1, SUB2	H10B0	H10B1	H10B2	H10B3	H10B4	H10B5

Table 2

	Value = 0	Value = 1	Value = 2	Value = 3
OUT1, OUT2**	Heating control	Cooling control	Proportional output	Disable output
SUB1, SUB2**	Heating control	Cooling control	Alarm output*	Disable output

Table 3

\* When there are only 3 channels of inputs, SUB1 cannot be used for alarm output but heating/cooling control only.

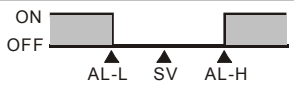
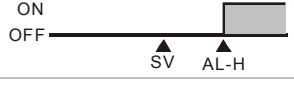
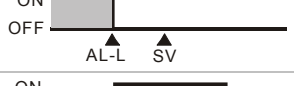
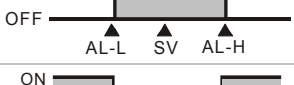
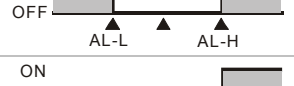


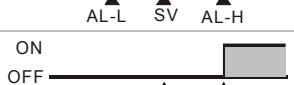
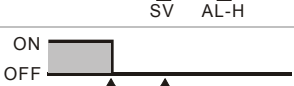
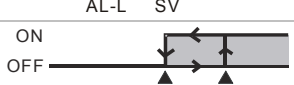
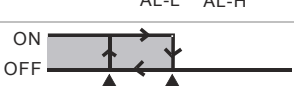
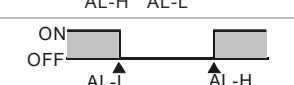

\*\* When there are only 3 channels of inputs, OUT2 and SUB2 cannot be set up by the user but set up automatically as "alarm output" by the controller.

### • Control Output:

DTE offers PID control, ON/OFF control, manual control and programmable PID control. Control output methods are set at address H10B8 ~ H10BF (default = 0: PID), PID parameters at H1028 ~ H105F, ON/OFF parameters at H1058 ~ H106F, and manual control parameters at H1070 ~ H107F.

### • Alarm Output:

DTE offers 13 alarm modes. The alarm modes are set up at address H10C0 ~ H10C7, upper limits at H1080 ~ H1087 and lower limits at H1088 ~ H108F.

SV	Alarm Mode	Alarm Output Operation
0	No alarm	Off
1	Alarm output is enabled when the temperature reaches upper and lower limits: The alarm will be enabled when PV exceeds $SV + AL-H$ or falls below $SV - AL-L$ .	
2	Alarm output will be enabled when the temperature reaches the upper limit: The alarm will be enabled when the PV exceeds $SV + AL-H$ .	
3	Alarm output will be enabled when the temperature reaches the lower limit: The alarm will be enabled when the PV falls below $SV - AL-L$ .	
4	Alarm output will be enabled when the PV is between $SV + AL-H$ and $SV - AL-L$ .	
5	Alarm output will be enabled when the temperature reaches the absolute value of the upper and lower limits: The alarm will be enabled when the PV exceeds $AL-H$ or falls below $AL-L$ .	
6	Alarm output will be enabled when the temperature reaches the absolute value of the upper limit: The alarm will be enabled when the PV exceeds $AL-H$ .	
7	Alarm output will be enabled when the temperature reaches the absolute value of the lower limit: The alarm will be enabled when the PV falls below $AL-L$ .	
8	Upper/lower limit standby alarm: The alarm will be enabled when the PV reaches SV and further exceeds $SV + AL-H$ or falls below $SV - AL-L$ .	
9	Upper limit standby alarm: The alarm will be enabled when the PV reaches SV and further exceeds $SV + AL-H$ .	
10	Lower limit standby alarm: The alarm will be enabled when the PV reaches SV and further falls below $SV - AL-L$ .	
11	Upper limit hysteresis alarm: The alarm will be enabled when the PV exceeds $SV + AL-H$ . The alarm will be disabled when the PV falls below $SV + AL-L$ .	
12	Lower limit hysteresis alarm: The alarm will be enabled when the PV falls below $SV - AL-H$ . The alarm will be disabled when the PV exceeds $SV - AL-L$ .	
13	CT alarm: The alarm will be enabled when the CT value exceeds $AL-H$ or falls below $AL-L$ .	

## ■ LED Display

PWR: On ⇒ DTE is powered.

RUN: On ⇒ Any of the channel is executing.

COM: Flashing ⇒ Communication in progress

ERR: Indicating errors (red)

ERR LED is on indicates one of the following errors occur, and the output has to be disabled.

1. Memory EEPROM error.
2. Any of the input points is not connected.
3. Any of the input points exceeds the setup range.
4. Any of the input temperatures has not been stabilized.

## ■ Synchronous Communication Protocol & Auto ID Setup

This function allows the auto setup of communication protocol in extension module DTC2000 and DTC2001 following the communication protocol set in the DTE main unit. The station IDs of DTC decrease. See below for the steps.

1. Set the auto communication ID of DTE as "1" (communication address: H10F8).
2. Switch off DTE. Connect DTE with extension module DTC2000, DTC2001 and switch on DTE again.
3. Default communication protocol: 9,600bps, 7 bits, Even, 1 stop bit, communication address = 01.
4. This function will consume 3 ~ 5 seconds more when you switch on DTE.

## ■ CT (Current Transformer)

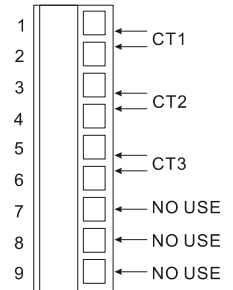
### ● Function

DTE10P offers maximum 3 channels of CT (CT1 ~ CT3), responsible for monitoring the current in INA.

Each CT group can be set up independently. With alarm outputs, when the detected current value is beyond the allowed range, the corresponding alarm will be enabled.

Slot INA offers 3 channels of input, and CH1 ~ CH3 correspond to the current detected at CT1 ~ CT3.

Hardware requirement: Accessory DTE2CT inserted in the slot AUX.



### ● How to Operate

1. Enable the CT function: Write 1234H into the address 47F1H and then 0004H into address 4824H.

bits in 4824H	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Flag	--	Hot runner control	Slope control	--	Latch	CT	EVENT	--

Notes:

- The flag to enable CT is at bit2 of 4824H. Write 0004H to bit2 to set it on.
  - If the "multistate" function is enabled, for example, writing in 0024H means enabling bit5 and bit2 at the same time.
  - You can only choose to use either the CT or EVENT function.
  - If there is already a set value in 4824H and you would like to modify it, reset it to 0 before you set up a new value.
2. When you use INA input or INA + INB input, set up relevant parameters using the table below.  
INA input:

INA	CH1	CH2	CH3
OUT1 control mode	10A8H	10A9H	10AAH
OUT2 control mode	10B0H	10B1H	10B2H
Alarm 1 output mode	10C0H	10C1H	10C2H
Alarm 2 output mode	10C4H	10C5H	10C6H
Upper bound of Alarm 1 output	1080H	1081H	1082H
Lower bound of Alarm 1 output	1088H	1089H	108AH
Upper bound of Alarm 2 output	1084H	1085H	1086H
Lower bound of Alarm 2 output	108CH	108DH	108EH
CT value (latch)	19A0H	19A1H	19A2H
CT value (dynamic)	19A4H	19A5H	19A6H

INA + INB input:

INA+INB	CH1	CH2	CH3	CH4	CH5	CH6
OUT1 control mode	10A8H	10A9H	10AAH	10ABH	10ACH	10ADH
Alarm 1 output mode	10C0H	10C1H	10C2H	10C3H	10C4H	10C5H
Upper bound of Alarm 1 output	1080H	1081H	1082H	1083H	1084H	1085H
Lower bound of Alarm 1 output	1088H	1089H	108AH	108BH	108CH	108DH
CT value (latch)	19A0H	19A1H	19A2H	--	--	--
CT value (dynamic)	19A4H	19A5H	19A6H	--	--	--

- OUT1 control mode has to be set to "0" (heating) or "1" (cooling). It cannot be set to "2" (proportional output).
- You can select Alarm 1 or Alarm 2 to be the output contact. The output mode has to be set to "13" (000DH).
- Adjust the upper/lower bound of the alarm output.
- The CT value will only be measured when there is OUT1 executing. If OUT1 does not exist, the previous CT value measured will be displayed.

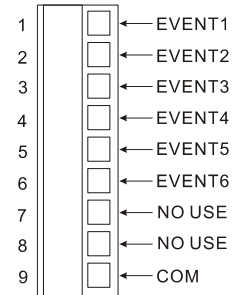
## ■ EVENT Input

### ● Function

DTE10P offers 6 channels of EVENT input (EV1 ~ EV6), and each EVENT can be set up independently. Slot number 1 ~ 6 in AUX on DTE10P correspond to EV1 ~ EV6.

EV1 to EV6 can be short-circuited individually with slot number 9 to switch functions.

Hardware requirement: Accessory DTE20D inserted in the slot AUX.



### ● How to Operate

- Enable the EVENT function: Write 1234H into the address 47F1H and then 0002H into address 4824H.

bits in 4824H	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Flag	--	Hot runner control	Slope control	--	Latch	CT	EVENT	--

Notes:

- The flag to enable EVENT is at bit1 of 4824H. Write 0002H to bit1 to set it on.
  - If the "multistate" function is enabled, for example, writing in 0022H means enabling bit5 and bit1 at the same time.
  - You can only choose to use either the CT or EVENT function.
  - If there is already a set value in 4824H and you would like to modify it, reset it to 0 before you set up a new value.
- Each channel can be set up individually for specific functions.

Addresses:

CH	CH1	CH2	CH3	CH4	CH5	CH6
Address for the EVENT function	1998H	1999H	199AH	199BH	199CH	199DH

Functions:

Set value	0	1	2	3	4
Function	N/A	RUN (open circuit) STOP (short circuit)	SV1 (open circuit) SV2 (short circuit)	Auto (open circuit) Manual (short circuit)	Execute (open circuit) Pause (short circuit)

Definitions:

- RUN/STOP: To enable or disable the output.
- SV1/SV2: To switch between set values.
- Auto/manual: To switch between the PID and manual controls.
- Execute/pause: To execute or pause the counting time when in programmable PID control.

Example: If you would like the function of EVENT1 at CH1 to be "SV1/SV2", write 0002H into address 1998H.

## ■ Slope

### ● Function

The temperature rises according to the slope set. Unit: 0.1°C/min.

Example: Suppose the slope is set to "50" and SV "200.0°C", then the temperature will rise at 5°C per minute until it reaches 200.0°C.

## • How to Operate

1. Enable the slope function: Write 1234H into the address 47F1H and then 0020H into address 4824H.

bits in 4824H	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Flag	--	Hot runner control	Slope control	--	Latch	CT	EVENT	--

Notes:

- The flag to enable slope function is at bit5 of 4824H. Write 0020H to bit5 to set it on.
  - If the “multistate” function is enabled, for example, writing 0022H means enabling bit5 and bit1 at the same time.
  - If there is already a set value in 4824H and you would like to modify it, reset it to 0 before you set up a new value.
2. Set up relevant parameters using the table below.

CH	CH1	CH2	CH3	CH4	CH5	CH6
Set value (SV)	1008H	1009H	100AH	100BH	100CH	100DH
Slope (unit: 0.1°)	1970H	1971H	1972H	1973H	1974H	1975H

Note: To stabilize the control, first execute auto-tuning when the slope function is selected. When auto-tuning is being executed, the slope control will stop.

## ■ Programmable PID Latch Function

### • Function

DTE10P offers programmable PID latch function. When the power is off and on again, the status before the power is cut off can be retained.

### • How to Operate

1. Enable the programmable PID latch function: Write 1234H into the address 47F1H and then 0008H into address 4824H.

bits in 4824H	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Flag	--	Hot runner control	Slope control	--	Latch	CT	EVENT	--

Notes:

- The flag to enable PID latch is at bit3 of 4824H. Write 0008H to bit3 to set it on.
- If the “multistate” function is enabled, for example, writing in 0028H means enabling bit5 and bit3 at the same time.
- If there is already a set value in 4824H and you would like to modify it, reset it to 0 before you set up a new value.

## ■ Opposite Output

### • Function

The 6 channels on DTE10P can be set to opposite output, that is, when the output is set to 0, the actual output will be 1.

### • How to Operate

To set CH1 and CH3 to opposite output, first write 1234H into the address 47F1H and then 0005H into address 4821H to set on CH1 (bit0) and CH3 (bit2).

CH6	CH5	CH4	CH3	CH2	CH1
Bit5	Bit4	Bit3	Bit2	Bit1	Bit0

## ■ Delayed Alarm

### • Function

When the set condition for alarms is met, the alarm will be enabled after a pre-set period of time.

### • How to Operate

Set up the time using the table below. Unit: second

CH	CH1	CH2	CH3	CH4	CH5	CH6
Address for delayed alarm	1990H	1991H	1992H	1993H	1994H	1995H

## ■ Output Limits

### ● Function

The output is limited between the maximum and minimum percentages.

### ● How to Operate

Set up relevant parameters using the table below.

CH	CH1	CH2	CH3	CH4	CH5	CH6
Max. output (%)	1980H	1981H	1982H	1983H	1984H	1985H
Min. output (%)	1988H	1989H	198AH	198BH	198CH	198DH

Note: When the output volume is limited at 20 to 80%, it means the output volume 0 to 100% calculated by the controller is corresponding to the actual output 20 to 80%.

## ■ Programmable Control Time Unit

### ● Function

The unit of programmable control time can be “minute” or “second”.

### ● How to Operate

Write 0 to the address to set the time unit to “minute” (default) or write 1 to set it to “second”.

CH	CH1	CH2	CH3	CH4	CH5	CH6
Address for time unit	1978H	1979H	197AH	197BH	197CH	197DH

## ■ Input Filter

### ● Function

To avoid unstable PV display due to interferences, DTE10P offers the filter function. Instead of averaging the values, the filter function here calculate the weighted average value of the “current PV” and “previous PV”.

**The filter equation: PV (displayed value) = [previous PV x (filter times – 1) + current PV] / filter times**

The bigger the filter times, the bigger the weight of the previous PV, and the smoother the temperature display, which is a good way to suppress interferences.

### ● How to Operate

Set up relevant parameters using the table below.

Parameter	Address	Default value	Range
Filter times	10F7H	8	0 ~ 50
Filter range	10F9H	1.0	0.1 ~ 10.0

## ■ Hot Runner Control

### ● Function

The hot runner control includes 3 steps:

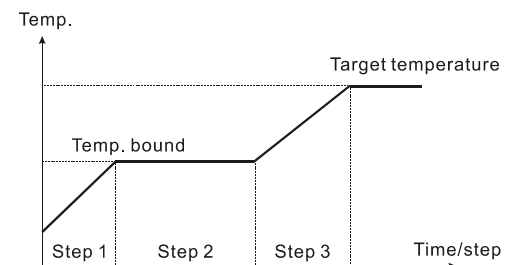
1. Heating up by constant output volume
2. Timed PID control (Soak)
3. Slope heating to the target temperature (SV)

### ● How to Operate

1. Enable the hot runner control function: Write 1234H into the address 47F1H and then 0060H into address 4824H.

bits in 4824H	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Flag	--	Hot runner control	Slope control	--	Latch	CT	EVENT	--

Notes:





- The flag to enable hot runner control is at bit6 of 4824H (and bit5 as to be enabled at the same time). Write 0060H to set both bits on.
  - If there is already a set value in 4824H and you would like to modify it, reset it to 0 before you set up a new value.
2. Set up relevant parameters using the table below.

CH	CH1	CH2	CH3	CH4	CH5	CH6
Temp. bound (unit: 0.1°)	1960H	1961H	1962H	1963H	1964H	1965H
Constant output volume (unit: 0.1%)	1968H	1969H	196AH	196BH	196CH	196DH
Timed time (unit: min.)	19B0H	19B1H	19B2H	19B3H	19B4H	19B5H
Target temperature (unit: 0.1°)	1008H	1009H	100AH	100BH	100CH	100DH
Slope (unit: 0.1°)	1970H	1971H	1972H	1973H	1974H	1975H

### • Example

Assume the temperature bound is 100.0, constant output volume is 35.0, timed time is 15, target temperature is 200.0 and slope is 20.0, thus

1. The heater outputs by the 35% constant volume and waits for the temperature to rise to 100 degrees,
2. When the temperature hits 100 degrees, switch to the PID soak mode and retain the temperature constantly for 15 minutes.
3. When the time is up, switch to the slope control mode, executing the condition of a 20 degree temperature rise every minute.
4. When the heating achieves 200 degrees, the hot runner control is completed.

## ■ RS-485 Communication

1. DTE supports baud rates 2,400/4,800/9,600/19,200/38,400/57,600/115,200 bps and does not support communication format 7, N, 1/8, E, 2/8, O, 2. Communication protocol = Modbus ASCII or RTU.
2. Function codes: 03H = read maximum 8 words in the register; 06H = write 1 word into the register.
3. Address and contents: Every parameter has 2 communication addresses. One is numbered by the function of the parameter, and the other is by the order of channel (as shown in the table below).

Content	Explanation	INA			INB		
		CH1	CH2	CH3	CH4	CH5	CH6
Present temperature value/input error code	Unit; 0.1 See Table 5	H1000 (H1100)	H1001 (H1200)	H1002 (H1300)	H1003 (H1400)	H1004 (H1500)	H1005 (H1600)
Set temperature value	Unit: 0.1	H1008 (H1101)	H1009 (H1201)	H100A (H1301)	H100B (H1401)	H100C (H1501)	H100D (H1601)
Max. temperature value	Disabled when higher than default value	H1010 (H1102)	H1011 (H1202)	H1012 (H1302)	H1013 (H1402)	H1014 (H1502)	H1015 (H1602)
Min. temperature value	Disabled when lower than default value	H1018 (H1103)	H1019 (H1203)	H101A (H1303)	H101B (H1403)	H101C (H1503)	H101D (H1603)
Error temperature value	-999 ~ +999 Unit: 0.1°C	H1020 (H1104)	H1021 (H1204)	H1022 (H1304)	H1023 (H1404)	H1024 (H1504)	H1025 (H1604)
Proportional band value (Pb)	0 ~ 9,999 Unit: 0.1	H1028 (H1105)	H1029 (H1205)	H102A (H1305)	H102B (H1405)	H102C (H1505)	H102D (H1605)
Ti value	0 ~ 9,999	H1030 (H1106)	H1031 (H1206)	H1032 (H1306)	H1033 (H1406)	H1034 (H1506)	H1035 (H1606)
Td value	0 ~ 9,999	H1038 (H1107)	H1039 (H1207)	H103A (H1307)	H103B (H1407)	H103C (H1507)	H103D (H1607)
Integration default	0.0 ~ 100.0% Unit: 0.1%	H1040 (H1108)	H1041 (H1208)	H1042 (H1308)	H1043 (H1408)	H1044 (H1508)	H1045 (H1608)
Proportional control offset error value, when Ti = 0	0.0 ~ 100.0% Unit: 0.1%	H1048 (H1109)	H1049 (H1209)	H104A (H1309)	H104B (H1409)	H104C (H1509)	H104D (H1609)
Proportional band coefficient of output 1 and output 2	0.01 ~ 99.99 Unit: 0.01	H1050 (H110A)	H1051 (H120A)	H1052 (H130A)	H1053 (H140A)	H1054 (H150A)	H1055 (H160A)
Dead band of control output 1 & output 2.	-99.9 ~ 999.9	H1058 (H110B)	H1059 (H120B)	H105A (H130B)	H105B (H140B)	H105C (H150B)	H105D (H160B)
Hysteresis for output 1	0 ~ 9,999 Unit: 0.1%	H1060 (H110C)	H1061 (H120C)	H1062 (H130C)	H1063 (H140C)	H1064 (H150C)	H1065 (H160C)
Hysteresis for output 2	0 ~ 9,999 Unit: 0.1%	H1068 (H110D)	H1069 (H120D)	H106A (H130D)	H106B (H140D)	H106C (H150D)	H106D (H160D)

Content	Explanation	INA			INB		
		CH1	CH2	CH3	CH4	CH5	CH6
Read/write output 1 value	Unit: 0.1 %	H1070 (H110E)	H1071 (H120E)	H1072 (H130E)	H1073 (H140E)	H1074 (H150E)	H1075 (H160E)
Read/write output 2 value	Unit: 0.1 %	H1078 (H110F)	H1079 (H120F)	H107A (H130F)	H107B (H140F)	H107C (H150F)	H107D (H160F)
Upper limit for alarm output	Alarm enabled when temperature exceeds upper limit	H1080 (H1110)	H1081 (1210)	H1082 (H1310)	H1083 (H1410)	H1084 (H1510)	H1085 (H1610)
Lower limit for alarm output	Alarm enabled when temperature falls below lower limit	H1088 (H1111)	H1089 (H1211)	H108A (H1311)	H108B (H1411)	H108C (H1511)	H108D (H1611)
Tuning for upper limit of analog output	Current (4 ~ 20mA) or voltage output tuning	H1090 (H1112)	H1091 (H1212)	H1092 (H1312)	H1093 (H1412)	H1094 (H1512)	H1095 (H1612)
Tuning for lower limit of analog output	Current (4 ~ 20mA) or voltage output tuning	H1098 (H1113)	H1099 (H1213)	H109A (H1313)	H109B (H1413)	H109C (H1513)	H109D (H1613)
Input sensor type	See "Input" section	H10A0 (H1114)	H10A1 (H1214)	H10A2 (H1314)	H10A3 (H1414)	H10A4 (H1514)	H10A5 (H1614)
Output function for output 1	0: heating 1: cooling 2: proportional output	H10A8 (H1115)	H10A9 (H1215)	H10AA (H1315)	H10AB (H1415)	H10AC (H1515)	H10AD (H1615)
Output function for output 2	0: heating (default) 1: cooling 2: alarm	H10B0 (H1116)	H10B1 (H1216)	H10B2 (H1316)	H10B3 (H1416)	H10B4 (H1516)	H10B5 (H1616)
Control method	0: PID 1: ON-OFF 2: manual 3: PID programmable	H10B8 (H1117)	H10B9 (H1217)	H10BA (H1317)	H10BB (H1417)	H10BC (H1517)	H10BD (H1617)
Alarm 1 output mode	See "Alarm Output" section	H10C0 (H1118)	H10C1 (H1218)	H10C2 (H1318)	H10C3 (H1418)	H10C4 (H1518)	H10C5 (H1618)
Alarm 2 output mode	See "Alarm Output" section	H10C4 (H1518)	H10C5 (H1618)	H10C6 (H1718)			
Heating/cooling cycle for output 1	1 ~ 99 seconds 0 = 0.5 second	H10C8 (H1119)	H10C9 (H1219)	H10CA (H1319)	H10CB (H1419)	H10CC (H1519)	H10CD (H1619)
Heating/cooling cycle for output 2	1 ~ 99 seconds 0 = 0.5 second	H10D0 (H111A)	H10D1 (H121A)	H10D2 (H131A)	H10D3 (H141A)	H10D4 (H151A)	H10D5 (H161A)
Run/Stop the control	0: stop 1: executing 2: program stops 3: program pauses	H10D8 (H111B)	H10D9 (H121B)	H10DA (H131B)	H10DB (H141B)	H10DC (H151B)	H10DD (H161B)
Status of PID auto-tuning	0: stop 1: executing	H10E0 (H111C)	H10E1 (H121C)	H10E2 (H131C)	H10E3 (H141C)	H10E4 (H151C)	H10E5 (H161C)
Positive/negative proportional output	0: positive 1: negative (slope)	H10E8 (H111D)	H10E9 (H121D)	H10EA (H131D)	H10EB (H141D)	H10EC (H151D)	H10ED (H161D)
LED status	b1: Alarm 2; b2: °C; b3:°F; b4: Alarm 1; b5: OUT2; b6: OUT1; b7: AT	H1124	H1224	H1324	H1424	H1524	H1624

Content	Explanation							
Other statuses	H10F0 Temperature unit	H10F1 Open special function (H1234)	H10F2 Return to default (H1357)	H10F3 Reserved	H10F4 Reserved	H10F5 Reserved	H10F6 Reserved	H10F7 Reserved
Communication specifications (See Table 4)	H10F8 Auto ID setup	H10F9 Reserved	H10FA Baud rate	H10FB ASCII = 0 RTU = 1	H10FC 8 bits = 0 7 bits = 1	H10FD 2 stop = 0 1 stop = 1	H10FE Parity bit	H10FF ID 1 ~ 247

## • Communication Parameter Setting

Content	0	1	2	3	4	5	6
Baudrate	2,400bps	4,800bps	9,600bps	19,200bps	38,400bps	57,600bps	115,200bps
Parity bit	None (N)	Even (E)	Odd (O)				

Table 4

## • Error Codes

The error codes can be read from address H1000 ~ H1007. When the input operation is in normal status, H1000 ~ H1007 are for input values. When input error occurs (except for stable status and input exceeding the range), DTE will read error codes in H8001 ~ H8002.

0x1000	Error description
0x8001	EEPROM cannot be written in.
0x8002	Input sensor is not connected.
0x8003	Group INB is not connected.

Table 5

**Returning to Default Value:** Write H1234 into address H10F1 and H1357 into address H10F2. Restart DTE.

## • Programmable Communication Parameter Setting

Content	Explanation	INA			INB		
		CH1	CH2	CH3	CH4	CH5	CH6
Read remaining time of the step	Unit: sec	H111E	H121E	H131E	H141E	H151E	H161E
Read remaining time of the step	Unit: min	H111F	H121F	H131F	H141F	H151F	H161F
Read the NO. of the current pattern	0 ~ 7	H1120	H1220	H1320	H1420	H1520	H1620
Read the NO. of the current step	0 ~ 7	H1121	H1221	H1321	H1421	H1521	H1621
NO. of start pattern	0 ~ 7	H1122	H1222	H1322	H1422	H1522	H1622
NO. of start step	0 ~ 7	H1123	H1223	H1323	H1423	H1523	H1623

## • Programmable Parameter Setting

Content	Explanation	Pattern 0	Pattern 1	Pattern 2	Pattern 3	Pattern 4	Pattern 5	Pattern 6	Pattern 7
Max. number of steps in the pattern	0 ~ 7 = N: The pattern executes from step 0 to N.	H2068	H2069	H206A	H206B	H206C	H206D	H206E	H206F
Number of cycles of pattern 0 ~ 7 execution	0 ~ 199: The pattern has been executed for 1 ~ 200 times	H2070	H2071	H2072	H2073	H2074	H2075	H2076	H2077
NO. of current link pattern	0 ~ 8: 8 refers to end of program; 0 ~ 7 refer to the NO. of next pattern	H2078	H2079	H207A	H207B	H207C	H207D	H207E	H207F

Address	Default	Content	Explanation
2000H ~ 203FH	0	Target temperatures for pattern 0 ~ 7 Pattern 0: 2000H ~ 2007H	Unit: 0.1°C
2080H ~ 20BFH	0	Execution time for pattern 0 ~ 7 Pattern 0: 2080H ~ 2087H	Time: 0 ~ 900 (Unit: 1 min)

4. Communication format: 03 = read bit data; 06 = write bit data

## • ASCII Mode

Read Command		Read Response Message		Write Command		Write Response Message	
Start word	':'	Start word	':'	Start word	':'	Start word	':'
Machine address 1	'0'	Machine address 1	'0'	Machine address 1	'0'	Machine address 1	'0'
Machine address 0	'1'	Machine address 0	'1'	Machine address 0	'1'	Machine address 0	'1'

Read Command		Read Response Message		Write Command		Write Response Message	
Command 1	'0'	Command 1	'0'	Command 1	'0'	Command 1	'0'
Command 0	'3'	Command 0	'3'	Command 0	'6'	Command 0	'6'
Read start address of data/bit	'1'	Length of response data (byte)	'0'	Data address	'1'	Data address	'1'
	'0'		'4'		'0'		'0'
	'0'		'0'		'0'		'0'
	'0'		'1'		'1'		'1'
Read length of data/bit (word/bit)	'0'	Data content in H1000	'F'	Write data content	'0'	Write data content	'0'
	'0'		'4'		'3'		'3'
	'0'		'0'		'E'		'E'
	'2'		'0'		'8'		'8'
LRC1 check	'E'	Data content in H1001	'0'	LRC1 check	'F'	LRC1 check	'F'
LRC0 check	'A'		'0'	LRC0 check	'D'	LRC0 check	'D'
End word 1	CR		LRC1 check	'0'	End word 1	CR	End word 1
End word 0	LF	LRC0 check	'3'	End word 0	LF	End word 0	LF
		End word 1	CR				
		End word 0	LF				

### • LRC Check

Sum up the contents from "machine address" to "data content", e.g. H01 + H03 + H10 + H00 + H00 + H02 = H16. Obtain 2's complement H EA.

### • RTU Mode

Read Command		Read Response Message		Write Command		Write Response Message	
Machine address	H01	Machine address	H01	Machine address	H01	Machine address	H01
Command	H03	Command	H03	Command	H06	Command	H06
Read start address of data	H10	Length of response data (byte)	H04	Write data address	H10	Write data address	H10
	H00				H01		H01
Read length of data (bit/word)	H00	Data content 1	H01	Write data content	H03	Write data content	H03
	H02		HF4		H20		H20
CRC low byte	HC0	Data content 2	H03	CRC low byte	HDD	CRC low byte	HDD
CRC high byte	HCB		H20	CRC high byte	HE2	CRC high byte	HE2
			CRC low byte	HBB			
		CRC high byte	H15				

**CRC (Cyclical Redundancy Check) is obtained by the following steps:**

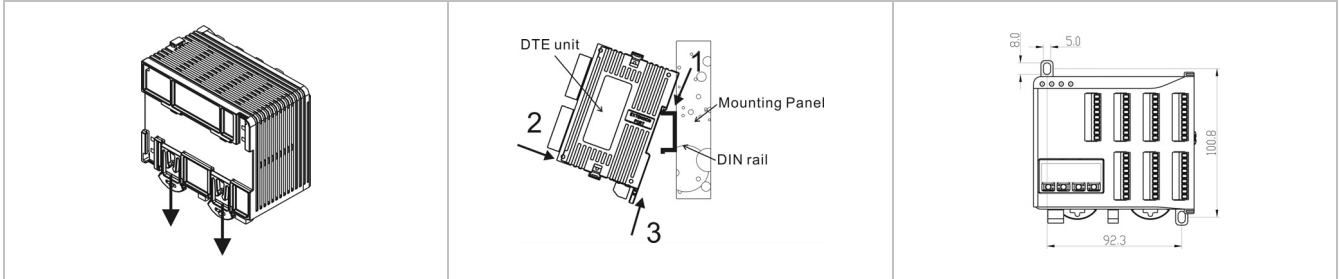
```

unsigned int reg_crc = 0xffff;
i = 0;
while (length--)
{ reg_crc ^= RTUData[i];
  i++;
  for (j = 0; j < 8; j++)
  { if (reg_crc & 0x01) reg_crc = (reg_crc >> 1) ^ 0xA001;
    else reg_crc = reg_crc >> 1;
  }
}
return(reg_crc);

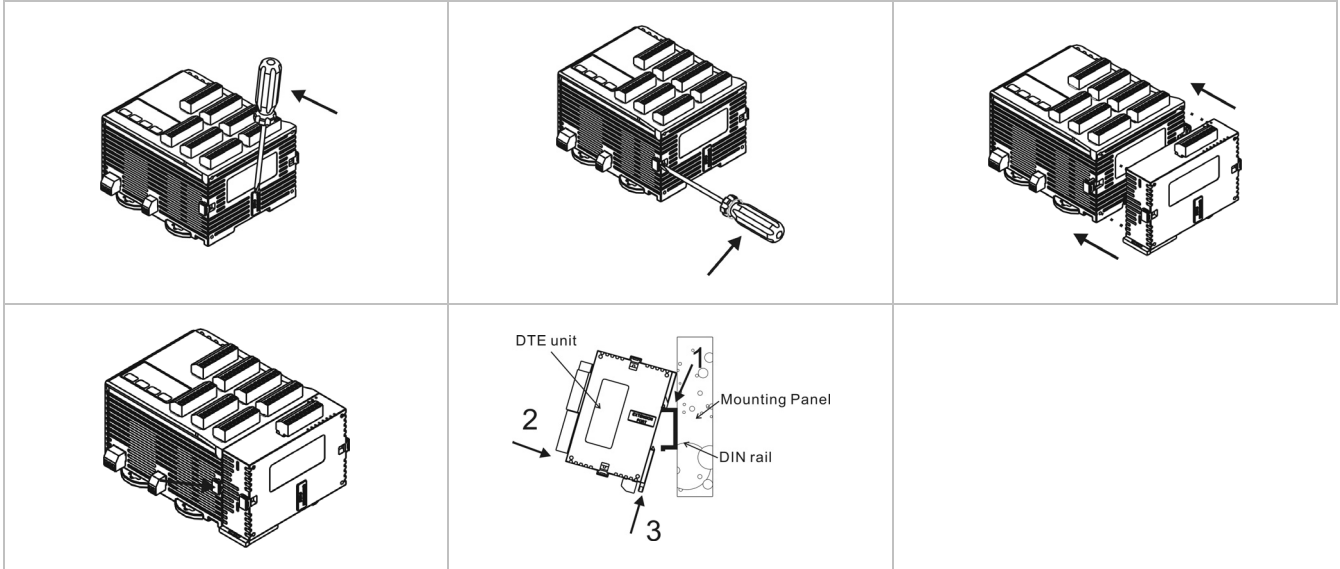
```

**Software for Setting up Communication on PC:** Download the free software on Delta's website.

## ■ How to Mount & DIN Rail Size



Connect maximum 7 DTC2000 or DTC2001 controllers to DTE by using DIN rail.





# DTE10T Series Temperature Controller Instruction Sheet

Thank you very much for choosing Delta DTE series temperature controller. Please read this instruction sheet carefully before using your DTE to ensure proper operation. Keep this instruction sheet handy for quick reference.

## ■ Precaution



### **DANGER! Caution! Electric Shock!**

DTE is an OPEN-TYPE device and therefore should be installed in an enclosure free of airborne dust, humidity, electric shock and vibration. The enclosure should prevent non-maintenance staff from operating the device (e.g. key or specific tools are required for opening the enclosure) in case danger and damage on the device may occur.



### **WARNING!**

1. Prevent dust or metallic debris from falling into the device and cause malfunctions. DO NOT modify or uninstall the circuit board of DTE without being permitted. DO NOT use empty terminals.
2. Keep away from high-voltage and high-frequency environment during the installation in case of interference. Prevent using the device in premises which contain:
  - (a) dust or corrosive gas; (b) high humidity and high radiation; (c) shock and vibration.
3. The power has to be switched off when wiring or changing the temperature sensor.
4. When installing the circuit board of the accessory, please make sure the power of the main unit is switched off and insert the accessory into the correct slot on the main unit.
5. Make sure to use compensation wire which matches the thermocouple or platinum resistance when extending or connecting the thermocouple or platinum resistance.
6. Keep the wire as short as possible when wiring a sensor to the controller. Separate the power cable and load wire in order to prevent interference and induced noise.
7. Make sure the power cables and signal device are installed correctly before switching on the power; otherwise serious damage may occur.
8. DO NOT touch the terminal or repair the device when the power is on; otherwise an electric shock may occur.
9. Please wait for 1 minute after the power is switched off to allow the capacitor to discharge and DO NOT touch the internal wiring within this period.
10. DO NOT touch the internal terminal when DTE is either switched on or off in case you may damage the circuit.
11. Please place DTE with other heating objects (e.g. power supply) within proper distance while installing DTE.

## ■ Ordering Information

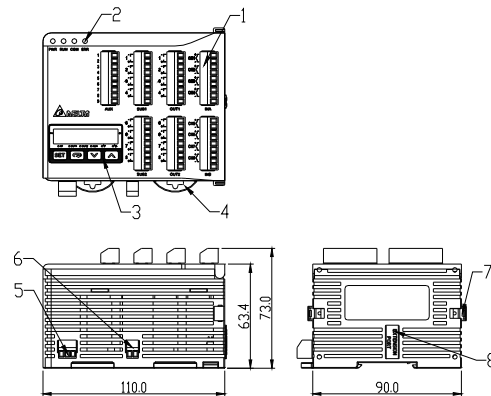
DTE 1 2 3 - 4

<b>Series name</b>	DTE: Delta E series temperature controller		
<span style="border: 1px solid black; padding: 0 2px;">1</span> <b>Device type</b>	1: main unit	2: accessory	
<span style="border: 1px solid black; padding: 0 2px;">2</span> <span style="border: 1px solid black; padding: 0 2px;">3</span> - <span style="border: 1px solid black; padding: 0 2px;">4</span>	OT: 4-channel TC OP: 3-channel PT	OT: 4-channel TC OV: 4 channels of voltage pulse output OC: 4 channels of linear current output OR: 4 channels of relay output OL: 4 channels of linear voltage output CT: 4 channels of current transformer sensors DS: Display and setup module	OP: 3-channel PT OD: 8-channel EVENT input

## ■ Specifications

Power input	24 VDC, isolated switching power supply
Voltage range	90 to 110% rated voltage
Power consumption	Max. 10 W + 3 W × number of DTC2000 controllers connected in parallel (Max. 7)
Input sensor	Thermocouple: K, J, T, E, N, R, S, B, L, U, TXK Platinum resistance: Pt100, JPt100, Cu50
Sampling cycle	Thermocouple or platinum resistance: 1.0 second/all input
Control method	PID, PID programmable, manual, ON/OFF
Output accessories (optional)	Relay output: SPST, Max. 250 VAC load, 3 A resistive load
	Voltage pulse output: 12 VDC, Max. 40 mA current output
	Current output: DC 4 to 20 mA output (resistive load < 500Ω); for OUT1 and OUT2 only
Output functions	Analog voltage output: 0 to 10V (resistive load > 1,000Ω); for OUT1 and OUT2 only
	Control output, alarm output or proportional output (proportional output is only applicable in the model with linear voltage and current output for OUT1, OUT2)
Alarm modes	13 alarm modes available
Communication	RS-485 digital communication; supports baudrate 2,400 to 115,200bps
Communication protocol	Supports Modbus ASCII/RTU
Extension port	The extension port transmits 24V power supply and communication signals to extension module DTC2000.
Vibration resistance	10 to 55Hz 10m/s <sup>2</sup> 3 axes 10mins
Shock resistance	Max. 300m/s <sup>2</sup> 3 axes 6 directions, 3 times each
Ambient temperature	0 to +50°C
Storage temperature	-20 to +65°C
Operation altitude	< 2,000m
Ambient humidity	35 to 85% RH (non-condensing)
Pollution degree	2

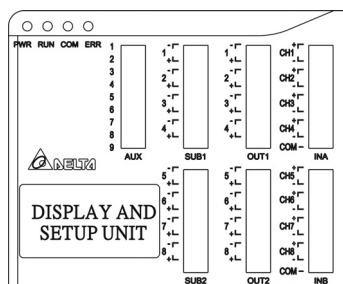
## ■ Product Profile & Outline



### DTE10T

- |   |                              |
|---|------------------------------|
| 1 | I/O terminals                |
| 2 | Status LED                   |
| 3 | Display and setup unit       |
| 4 | DIN rail clip                |
| 5 | Power input port             |
| 6 | RS-485 communication port    |
| 7 | Extension module fixing clip |
| 8 | Extension port               |

## ■ Panel Layout



## ■ Input

The standard DTE main unit is attached with 4 channels of inputs. You can purchase additional DTE20T or DTE20P to expand the number of input channels. DTE supports maximum 8 channels of inputs which belong to group INA and group INB. Each group possesses 4 input channels.

DTE series supports the following input sensors:

Input Sensor Type	Register Value	Range
For DTE10P / DTE20P		
Temperature measurement resistance (Cu50)	13	-50 ~ 150°C
Platinum resistance (Pt100)	12	-200 ~ 600°C
Platinum resistance (JPT100)	11	-20 ~ 400°C
For DTE10T / DTE20T		
Thermocouple TXK type	10	-200 ~ 800°C
Thermocouple U type	9	-200 ~ 500°C
Thermocouple L type	8	-200 ~ 850°C
Thermocouple B type	7	100 ~ 1,800°C
Thermocouple S type	6	0 ~ 1,700°C
Thermocouple R type	5	0 ~ 1,700°C
Thermocouple N type	4	-200 ~ 1,300°C
Thermocouple E type	3	0 ~ 600°C
Thermocouple T type	2	-200 ~ 400°C
Thermocouple J type	1	-100 ~ 1,200°C
Thermocouple K type	0	-200 ~ 1,300°C

Note: The default setting in DTE10T is "thermocouple K type". The default setting in DTE10P is "Pt100".

Communication address: Input sensor types at H10A0 ~ H10A7; input upper limits at H1010 ~ H1017; input lower limits at H1018 ~ H101F.

## ■ Output

DTE supports maximum 16 channels of outputs, belonging to output groups OUT1, OUT2, SUB1 and SUB2, each group with 4 channels. See the explanations below for how input channels correspond to output groups.

- Without group INB (4 channels of input): Every channel corresponds to 2 groups of output and 2 groups of alarms. OUT1 and SUB1 are for control output, and OUT2 and SUB2 are fixed for alarm output.
- With group INB (8 channels of input): Every channel is paired with 2 groups of outputs. OUT1 and OUT2 are used for control output or proportional output of CH1 ~ CH8. SUB1 and SUB2 are used for control output or alarm output.

See Table 1 for the relations between input and output.

Output Group	4 channels of input	8 channels of input	
	INA (CH1 ~ CH4)	INA (CH1 ~ CH4)	INB (CH5 ~ CH8)
OUT1	Main control output or proportional output	Main control output or proportional output	No corresponding output
OUT2	Alarm 1 output	No corresponding output	Main control output or proportional output
SUB1	Control output	Control output or alarm output	No corresponding output
SUB2	Alarm 2 output	No corresponding output	Control output or alarm output

Table 1

Note: SUB1 and SUB2 do not support DTE20L and DTE20C. Please install the optional output modules you purchase into the correct slot.

### ● Communication Address of Output & How to Set up Parameters

See Table 2 for the communication addresses of output and Table 3 for the definition of the value in the address.

	INA				INB			
	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
OUT1, OUT2	H10A8	H10A9	H10AA	H10AB	H10AC	H10AD	H10AE	H10AF
SUB1, SUB2	H10B0	H10B1	H10B2	H10B3	H10B4	H10B5	H10B6	H10B7

Table 2



	Value = 0	Value = 1	Value = 2	Value = 3
OUT1, OUT2**	Heating control	Cooling control	Proportional output	Disable output
SUB1, SUB2**	Heating control	Cooling control	Alarm output*	Disable output

Table 3

\*When there are only 4 channels of inputs, SUB1 cannot be used for alarm output but heating/cooling control only.

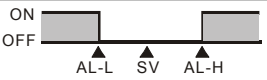
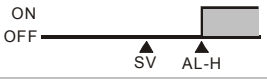
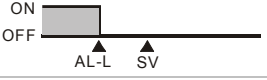
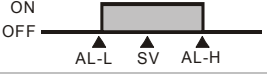



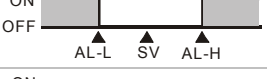
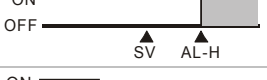
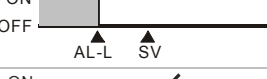
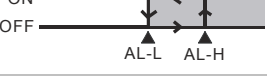


\*\*When there are only 4 channels of inputs, OUT2 and SUB2 cannot be set up by the user but set up automatically as "alarm output" by the controller.

### • Control Output

DTE offers PID control, ON/OFF control, manual control and programmable PID control. Control output methods are set at address H10B8 ~ H10BF (default = 0: PID), PID parameters at H1028 ~ H105F, ON/OFF parameters at H1058 ~ H106F, and manual control parameters at H1070 ~ H107F.

### • Alarm Output

DTE offers 13 alarm modes. The alarm modes are set up at address H10C0 ~ H10C7, upper limits at H1080 ~ H1087 and lower limits at H1088 ~ H108F.

SV	Alarm Mode	Alarm Output Operation
0	No alarm	Off
1	Alarm output is enabled when the temperature reaches upper and lower limits: The alarm will be enabled when PV exceeds $SV + AL-H$ or falls below $SV - AL-L$ .	
2	Alarm output will be enabled when the temperature reaches the upper limit: The alarm will be enabled when the PV exceeds $SV + AL-H$ .	
3	Alarm output will be enabled when the temperature reaches the lower limit: The alarm will be enabled when the PV falls below $SV - AL-L$ .	
4	Alarm output will be enabled when the PV is between $SV + AL-H$ and $SV - AL-L$ .	
5	Alarm output will be enabled when the temperature reaches the absolute value of the upper and lower limits: The alarm will be enabled when the PV exceeds $AL-H$ or falls below $AL-L$ .	
6	Alarm output will be enabled when the temperature reaches the absolute value of the upper limit: The alarm will be enabled when the PV exceeds $AL-H$ .	
7	Alarm output will be enabled when the temperature reaches the absolute value of the lower limit: The alarm will be enabled when the PV falls below $AL-L$ .	
8	Upper/lower limit standby alarm: The alarm will be enabled when the PV reaches SV and further exceeds $SV + AL-H$ or falls below $SV - AL-L$ .	
9	Upper limit standby alarm: The alarm will be enabled when the PV reaches SV and further exceeds $SV + AL-H$ .	
10	Lower limit standby alarm: The alarm will be enabled when the PV reaches SV and further falls below $SV - AL-L$ .	
11	Upper limit hysteresis alarm: The alarm will be enabled when the PV exceeds $SV + AL-H$ . The alarm will be disabled when the PV falls below $SV + AL-L$ .	
12	Lower limit hysteresis alarm: The alarm will be enabled when the PV falls below $SV - AL-H$ . The alarm will be disabled when the PV exceeds $SV - AL-L$ .	
13	CT alarm: The alarm will be enabled when the CT value exceeds $AL-H$ or falls below $AL-L$ .	

## ■ LED Display

PWR: On ⇒ DTE is powered.

RUN: On ⇒ Any of the channel is executing.

COM: Flashing ⇒ Communication in progress

ERR: Indicating errors (red)

ERR LED is on indicates one of the following errors occur, and the output has to be disabled.

1. Memory EEPROM error.
2. Any of the input points is not connected.
3. Any of the input points exceeds the setup range.
4. Any of the input temperatures has not been stabilized.

## ■ Synchronous Communication Protocol & Auto ID Setup

This function allows the auto setup of communication protocol in extension module DTC2000 and DTC2001 following the communication protocol set in the DTE main unit. The station IDs of DTC decrease. See below for the steps.

1. Set the auto communication ID of DTE as "1" (communication address: H10F8).
2. Switch off DTE. Connect DTE with extension module DTC2000, DTC2001 and switch on DTE again.
3. Default communication protocol: 9,600bps, 7 bits, Even, 1 stop bit, communication address = 01.
4. This function will consume 3 ~ 5 seconds more when you switch on DTE.

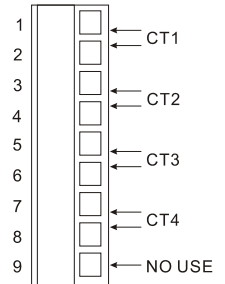
## ■ CT (Current Transformer)

### ● Function

DTE10T offers maximum 4 channels of CT (CT1 ~ CT4), responsible for monitoring the current in INA. Each CT group can be set up independently. With alarm outputs, when the detected current value is beyond the allowed range, the corresponding alarm will be enabled.

Slot INA offers 4 channels of input, and CH1 ~ CH4 correspond to the current detected at CT1 ~ CT4.

Hardware requirement: Accessory DTE2CT inserted in the slot AUX.



### ● How to Operate

1. Enable the CT function: Write 1234H into the address 47F1H and then 0004H into address 4824H.

bits in 4824H	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Flag	--	Hot runner control	Slope control	--	Latch	CT	EVENT	--

Notes:

- The flag to enable CT is at bit2 of 4824H. Write 0004H to bit2 to set it on.
  - If the "multistate" function is enabled, for example, writing in 0024H means enabling bit5 and bit2 at the same time.
  - You can only choose to use either the CT or EVENT function.
  - If there is already a set value in 4824H and you would like to modify it, reset it to 0 before you set up a new value.
2. When you use INA input or INA + INB input, set up relevant parameters using the table below.  
INA input:

INA	CH1	CH2	CH3	CH4
OUT1 control mode	10A8H	10A9H	10AAH	10ABH
OUT2 control mode	10B0H	10B1H	10B2H	10B3H
Alarm 1 output mode	10C0H	10C1H	10C2H	10C3H
Alarm 2 output mode	10C4H	10C5H	10C6H	10C7H
Upper bound of Alarm 1 output	1080H	1081H	1082H	1083H
Lower bound of Alarm 1 output	1088H	1089H	108AH	108BH
Upper bound of Alarm 2 output	1084H	1085H	1086H	1087H
Lower bound of Alarm 2 output	108CH	108DH	108EH	108FH
CT value (latch)	19A0H	19A1H	19A2H	19A3H
CT value (dynamic)	19A4H	19A5H	19A6H	19A7H

INA + INB input:

INA+INB	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
OUT1 control mode	10A8H	10A9H	10AAH	10ABH	10ACH	10ADH	10AEH	10AFH
Alarm 1 output mode	10C0H	10C1H	10C2H	10C3H	10C4H	10C5H	10C6H	10C7H
Upper bound of Alarm 1 output	1080H	1081H	1082H	1083H	1084H	1085H	1086H	1087H
Lower bound of Alarm 1 output	1088H	1089H	108AH	108BH	108CH	108DH	108EH	108FH
CT value (latch)	19A0H	19A1H	19A2H	19A3H	--	--	--	--
CT value (dynamic)	19A4H	19A5H	19A6H	19A7H	--	--	--	--

- OUT1 control mode has to be set to "0" (heating) or "1" (cooling). It cannot be set to "2" (proportional output).
- You can select Alarm 1 or Alarm 2 to be the output contact. The output mode has to be set to "13" (000DH).
- Adjust the upper/lower bound of the alarm output.
- The CT value will only be measured when there is OUT1 executing. If OUT1 does not exist, the previous CT value measured will be displayed.

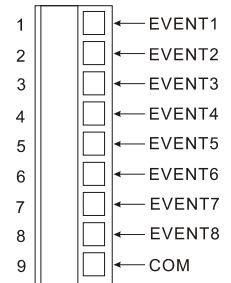
## ■ EVENT Input

### ● Function

DTE10T offers 8 channels of EVENT input (EV1 ~ EV8), and each EVENT can be set up independently. Slot number 1 ~ 8 in AUX on DTE10T correspond to EV1 ~ EV8.

EV1 to EV8 can be short-circuited individually with slot number 9 to switch functions.

Hardware requirement: Accessory DTE20D inserted in the slot AUX.



### ● How to Operate

- Enable the EVENT function: Write 1234H into the address 47F1H and then 0002H into address 4824H.

bits in 4824H	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Flag	--	Hot runner control	Slope control	--	Latch	CT	EVENT	--

Notes:

- The flag to enable EVENT is at bit1 of 4824H. Write 0002H to bit1 to set it on.
  - If the "multistate" function is enabled, for example, writing in 0022H means enabling bit5 and bit1 at the same time.
  - You can only choose to use either the CT or EVENT function.
  - If there is already a set value in 4824H and you would like to modify it, reset it to 0 before you set up a new value.
- Each channel can be set up individually for specific functions.

Addresses:

CH	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Address for the EVENT function	1998H	1999H	199AH	199BH	199CH	199DH	199EH	199FH

Functions:

Set value	0	1	2	3	4
Function	N/A	RUN (open circuit) STOP (short circuit)	SV1 (open circuit) SV2 (short circuit)	Auto (open circuit) Manual (short circuit)	Execute (open circuit) Pause (short circuit)

Definitions:

- RUN/STOP: To enable or disable the output.
- SV1/SV2: To switch between set values.
- Auto/manual: To switch between the PID and manual controls.
- Execute/pause: To execute or pause the counting time when in programmable PID control.

Example: If you would like the function of EVENT1 at CH1 to be "SV1/SV2", write 0002H into address 1998H.

## ■ Slope

### ● Function

The temperature rises according to the slope set. Unit: 0.1°C/min.

Example: Suppose the slope is set to "50" and SV "200.0°C", then the temperature will rise at 5°C per minute until it reaches 200.0°C.

## • How to Operate

1. Enable the slope function: Write 1234H into the address 47F1H and then 0020H into address 4824H.

bits in 4824H	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Flag	--	Hot runner control	Slope control	--	Latch	CT	EVENT	--

Notes:

- The flag to enable slope function is at bit5 of 4824H. Write 0020H to bit5 to set it on.
  - If the “multistate” function is enabled, for example, writing 0022H means enabling bit5 and bit1 at the same time.
  - If there is already a set value in 4824H and you would like to modify it, reset it to 0 before you set up a new value.
2. Set up relevant parameters using the table below.

CH	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Set value (SV)	1008H	1009H	100AH	100BH	100CH	100DH	100EH	100FH
Slope (unit: 0.1°)	1970H	1971H	1972H	1973H	1974H	1975H	1976H	1977H

Note: To stabilize the control, first execute auto-tuning when the slope function is selected. When auto-tuning is being executed, the slope control will stop.

## ■ Programmable PID Latch Function

### • Function

DTE10T offers programmable PID latch function. When the power is off and on again, the status before the power is cut off can be retained.

### • How to Operate

1. Enable the programmable PID latch function: Write 1234H into the address 47F1H and then 0008H into address 4824H.

bits in 4824H	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Flag	--	Hot runner control	Slope control	--	Latch	CT	EVENT	--

Notes:

- The flag to enable PID latch is at bit3 of 4824H. Write 0008H to bit3 to set it on.
- If the “multistate” function is enabled, for example, writing in 0028H means enabling bit5 and bit3 at the same time.
- If there is already a set value in 4824H and you would like to modify it, reset it to 0 before you set up a new value.

## ■ Opposite Output

### • Function

The 8 channels on DTE10T can be set to opposite output, that is, when the output is set to 0, the actual output will be 1.

### • How to Operate

To set CH1 and CH3 to opposite output, first write 1234H into the address 47F1H and then 0005H into address 4821H to set on CH1 (bit0) and CH3 (bit2).

CH8	CH7	CH6	CH5	CH4	CH3	CH2	CH1
Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0

## ■ Delayed Alarm

### • Function

When the set condition for alarms is met, the alarm will be enabled after a pre-set period of time.

### • How to Operate

Set up the time using the table below. Unit: second

CH	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Address for delayed alarm	1990H	1991H	1992H	1993H	1994H	1995H	1996H	1997H

## ■ Output Limits

### ● Function

The output is limited between the maximum and minimum percentages.

### ● How to Operate

Set up relevant parameters using the table below.

CH	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Max. output (%)	1980H	1981H	1982H	1983H	1984H	1985H	1986H	1987H
Min. output (%)	1988H	1989H	198AH	198BH	198CH	198DH	198EH	198FH

Note: When the output volume is limited at 20 to 80%, it means the output volume 0 to 100% calculated by the controller is corresponding to the actual output 20 to 80%.

## ■ Programmable Control Time Unit

### ● Function

The unit of programmable control time can be “minute” or “second”.

### ● How to Operate

Write 0 to the address to set the time unit to “minute” (default) or write 1 to set it to “second”.

CH	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Address for time unit	1978H	1979H	197AH	197BH	197CH	197DH	197EH	197FH

## ■ Input Filter

### ● Function

To avoid unstable PV display due to interferences, DTE10T offers the filter function. Instead of averaging the values, the filter function here calculate the weighted average value of the “current PV” and “previous PV”.

**The filter equation: PV (displayed value) = [previous PV x (filter times – 1) + current PV] / filter times**

The bigger the filter times, the bigger the weight of the previous PV, and the smoother the temperature display, which is a good way to suppress interferences.

### ● How to Operate

Set up relevant parameters using the table below.

Parameter	Address	Default value	Range
Filter times	10F7H	8	0 ~ 50
Filter range	10F9H	1.0	0.1 ~ 10.0

## ■ Hot Runner Control

### ● Function

The hot runner control includes 3 steps:

1. Heating up by constant output volume
2. Timed PID control (Soak)
3. Slope heating to the target temperature (SV)

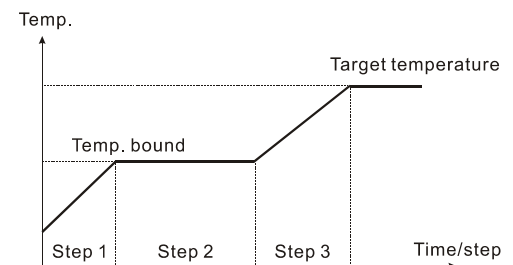
### ● How to Operate

1. Enable the hot runner control function: Write 1234H into the address 47F1H and then 0060H into address 4824H.

bits in 4824H	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Flag	--	Hot runner control	Slope control	--	Latch	CT	EVENT	--

Notes:

- The flag to enable hot runner control is at bit6 of 4824H (and bit5 as to be enabled at the same time). Write 0060H to set both bits on.



- If there is already a set value in 4824H and you would like to modify it, reset it to 0 before you set up a new value.
2. Set up relevant parameters using the table below.

CH	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Temp. bound (unit: 0.1°)	1960H	1961H	1962H	1963H	1964H	1965H	1966H	1967H
Constant output volume (unit: 0.1%)	1968H	1969H	196AH	196BH	196CH	196DH	196EH	196FH
Timed time (unit: min.)	19B0H	19B1H	19B2H	19B3H	19B4H	19B5H	19B6H	19B7H
Target temperature (unit: 0.1°)	1008H	1009H	100AH	100BH	100CH	100DH	100EH	100FH
Slope (unit: 0.1°)	1970H	1971H	1972H	1973H	1974H	1975H	1976H	1977H

### • Example

Assume the temperature bound is 100.0, constant output volume is 35.0, timed time is 15, target temperature is 200.0 and slope is 20.0, thus

1. The heater outputs by the 35% constant volume and waits for the temperature to rise to 100 degrees,
2. When the temperature hits 100 degrees, switch to the PID soak mode and retain the temperature constantly for 15 minutes.
3. When the time is up, switch to the slope control mode, executing the condition of a 20 degree temperature rise every minute.
4. When the heating achieves 200 degrees, the hot runner control is completed.

## ■ RS-485 Communication

1. DTE supports baudrates 2,400/4,800/9,600/19,200/38,400/57,600/115,200 bps and does not support communication format 7, N, 1/8, E, 2/8, O, 2. Communication protocol = Modbus ASCII or RTU.
2. Function codes: H03 = read maximum 8 words in the register; H06 = write 1 word into the register.
3. Address and contents: Every parameter has 2 communication addresses. One is numbered by the function of the parameter, and the other is by the order of channel (as shown in the table below).

Content	Explanation	INA				INB			
		CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Present temperature value/input error code	Unit: 0.1 See Table 5	H1000 (H1100)	H1001 (H1200)	H1002 (H1300)	H1003 (H1400)	H1004 (H1500)	H1005 (H1600)	H1006 (H1700)	H1007 (H1800)
Set temperature value	Unit: 0.1	H1008 (H1101)	H1009 (H1201)	H100A (H1301)	H100B (H1401)	H100C (H1501)	H100D (H1601)	H100E (H1701)	H100F (H1801)
Max. temperature value	Disabled when higher than default value	H1010 (H1102)	H1011 (H1202)	H1012 (H1302)	H1013 (H1402)	H1014 (H1502)	H1015 (H1602)	H1016 (H1702)	H1017 (H1802)
Min. temperature value	Disabled when lower than default value	H1018 (H1103)	H1019 (H1203)	H101A (H1303)	H101B (H1403)	H101C (H1503)	H101D (H1603)	H101E (H1703)	H101F (H1803)
Error temperature value	-999 ~ +999 Unit: 0.1°C	H1020 (H1104)	H1021 (H1204)	H1022 (H1304)	H1023 (H1404)	H1024 (H1504)	H1025 (H1604)	H1026 (H1704)	H1027 (H1804)
Proportional band value (Pb)	0 ~ 9,999 Unit: 0.1	H1028 (H1105)	H1029 (H1205)	H102A (H1305)	H102B (H1405)	H102C (H1505)	H102D (H1605)	H102E (H1705)	H102F (H1805)
Ti value	0 ~ 9,999	H1030 (H1106)	H1031 (H1206)	H1032 (H1306)	H1033 (H1406)	H1034 (H1506)	H1035 (H1606)	H1036 (H1706)	H1037 (H1806)
Td value	0 ~ 9,999	H1038 (H1107)	H1039 (H1207)	H103A (H1307)	H103B (H1407)	H103C (H1507)	H103D (H1607)	H103E (H1707)	H103F (H1807)
Integration default	0.0 ~ 100.0% Unit: 0.1%	H1040 (H1108)	H1041 (H1208)	H1042 (H1308)	H1043 (H1408)	H1044 (H1508)	H1045 (H1608)	H1046 (H1708)	H1010 (H1808)
Proportional control offset error value, when Ti = 0	0.0 ~ 100.0% Unit: 0.1%	H1048 (H1109)	H1049 (H1209)	H104A (H1309)	H104B (H1409)	H104C (H1509)	H104D (H1609)	H104E (H1709)	H104F (H1809)
Proportional band coefficient of output 1 and output 2	0.01 ~ 99.99 Unit: 0.01	H1050 (H110A)	H1051 (H120A)	H1052 (H130A)	H1053 (H140A)	H1054 (H150A)	H1055 (H160A)	H1056 (H170A)	H1057 (H180A)
Dead band of control output 1 & output 2.	-99.9 ~ 999.9	H1058 (H110B)	H1059 (H120B)	H105A (H130B)	H105B (H140B)	H105C (H150B)	H105D (H160B)	H105E (H170B)	H105F (H180B)
Hysteresis for output 1	0 ~ 9,999 Unit: 0.1%	H1060 (H110C)	H1061 (H120C)	H1062 (H130C)	H1063 (H140C)	H1064 (H150C)	H1065 (H160C)	H1066 (H170C)	H1067 (H180C)
Hysteresis for output 2	0 ~ 9,999 Unit: 0.1%	H1068 (H110D)	H1069 (H120D)	H106A (H130D)	H106B (H140D)	H106C (H150D)	H106D (H160D)	H106E (H170D)	H106F (H180D)

Content	Explanation	INA				INB			
		CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Read/write output 1 value	Unit: 0.1 %	H1070 (H110E)	H1071 (H120E)	H1072 (H130E)	H1073 (H140E)	H1074 (H150E)	H1075 (H160E)	H1076 (H170E)	H1077 (H180E)
Read/write output 2 value	Unit: 0.1 %	H1078 (H110F)	H1079 (H120F)	H107A (H130F)	H107B (H140F)	H107C (H150F)	H107D (H160F)	H107E (H170F)	H107F (H180F)
Upper limit for alarm output	Alarm enabled when temperature exceeds upper limit	H1080 (H1110)	H1081 (1210)	H1082 (H1310)	H1083 (H1410)	H1084 (H1510)	H1085 (H1610)	H1086 (H1710)	H1087 (H1810)
Lower limit for alarm output	Alarm enabled when temperature falls below lower limit	H1088 (H1111)	H1089 (H1211)	H108A (H1311)	H108B (H1411)	H108C (H1511)	H108D (H1611)	H108E (H1711)	H108F (H1811)
Tuning for upper limit of analog output	Current (4 ~ 20mA) or voltage output tuning	H1090 (H1112)	H1091 (H1212)	H1092 (H1312)	H1093 (H1412)	H1094 (H1512)	H1095 (H1612)	H1096 (H1712)	H1097 (H1812)
Tuning for lower limit of analog output	Current (4 ~ 20mA) or voltage output tuning	H1098 (H1113)	H1099 (H1213)	H109A (H1313)	H109B (H1413)	H109C (H1513)	H109D (H1613)	H109E (H1713)	H109F (H1813)
Input sensor type	See "Input" section	H10A0 (H1114)	H10A1 (H1214)	H10A2 (H1314)	H10A3 (H1414)	H10A4 (H1514)	H10A5 (H1614)	H10A6 (H1714)	H10A7 (H1814)
Output function for output 1	0: heating 1: cooling 2: proportional output	H10A8 (H1115)	H10A9 (H1215)	H10AA (H1315)	H10AB (H1415)	H10AC (H1515)	H10AD (H1615)	H10AE (H1715)	H10AF (H1815)
Output function for output 2	0: heating (default) 1: cooling 2: alarm	H10B0 (H1116)	H10B1 (H1216)	H10B2 (H1316)	H10B3 (H1416)	H10B4 (H1516)	H10B5 (H1616)	H10B6 (H1716)	H10B7 (H1816)
Control method	0: PID 1: ON-OFF 2: manual 3: PID programmable	H10B8 (H1117)	H10B9 (H1217)	H10BA (H1317)	H10BB (H1417)	H10BC (H1517)	H10BD (H1617)	H10BE (H1717)	H10BF (H1817)
Alarm 1 output mode	See "Alarm Output" section	H10C0 (H1118)	H10C1 (H1218)	H10C2 (H1318)	H10C3 (H1418)	H10C4 (H1518)	H10C5 (H1618)	H10C6 (H1718)	H10C7 (H1818)
Alarm 2 output mode	See "Alarm Output" section	H10C4 (H1518)	H10C5 (H1618)	H10C6 (H1718)	H10C7 (H1818)				
Heating/cooling cycle for output 1	1 ~ 99 seconds 0 = 0.5 second	H10C8 (H1119)	H10C9 (H1219)	H10CA (H1319)	H10CB (H1419)	H10CC (H1519)	H10CD (H1619)	H10CE (H1719)	H10CF (H1819)
Heating/cooling cycle for output 2	1 ~ 99 seconds 0 = 0.5 second	H10D0 (H111A)	H10D1 (H121A)	H10D2 (H131A)	H10D3 (H141A)	H10D4 (H151A)	H10D5 (H161A)	H10D6 (H171A)	H10D7 (H181A)
Run/Stop the control	0: stop 1: executing 2: program stops 3: program pauses	H10D8 (H111B)	H10D9 (H121B)	H10DA (H131B)	H10DB (H141B)	H10DC (H151B)	H10DD (H161B)	H10DE (H171B)	H10DF (H181B)
Status of PID auto-tuning	0: stop 1: executing	H10E0 (H111C)	H10E1 (H121C)	H10E2 (H131C)	H10E3 (H141C)	H10E4 (H151C)	H10E5 (H161C)	H10E6 (H171C)	H10E7 (H181C)
Positive/negative proportional output	0: positive 1: negative (slope)	H10E8 (H111D)	H10E9 (H121D)	H10EA (H131D)	H10EB (H141D)	H10EC (H151D)	H10ED (H161D)	H10EE (H171D)	H10EF (H181D)
Other statuses	Other statuses	H10F0 Temperature unit	H10F1 Open special function (H1234)	H10F2 Return to default (H1357)	H10F3 Reserved	H10F4 Reserved	H10F5 Reserved	H10F6 Reserved	H10F7 Reserved
Communication specifications	See Table 4	H10F8 Auto ID setup	H10F9 Reserved	H10FA Baudrate	H10FB ASCII = 0 RTU = 1	H10FC 8 bits=0 7 bits=1	H10FD 2 stop=0 1 stop=1	H10FE Parity	H10FF Address 1 ~ 247
LED status	b1: Alarm 2; b2: °C; b3: °F; b4: Alarm 1; b5: OUT2; b6: OUT1; b7: AT	H1124	H1224	H1324	H1424	H1524	H1624	H1724	H1824

## • Communication Parameter Setting

Content	0	1	2	3	4	5	6
Baudrate	2,400bps	4,800bps	9,600bps	19,200bps	38,400bps	57,600bps	115,200bps
Parity bit	None (N)	Even (E)	Odd (O)				

Table 4

## • Error Codes

The error codes can be read from address H1000 ~ H1007. When the input operation is in normal status, H1000 ~ H1007 are for input values. When input error occurs (except for stable status and input exceeding the range), DTE will read error codes in H8001 ~ H8002.

H1000	Error description
H8001	EEPROM cannot be written in.
H8002	Input sensor is not connected.
H8003	Group INB is not connected.

Table 5

**Analog output current tuning scale:** 1 $\mu$ A/scale

**Analog output voltage tuning scale:** 1mV/scale

**Returning to Default Value:** Write H1234 into address H10F1 and H1357 into address H10F2. Restart DTE.

## • Programmable Communication Parameter Setting

Content	Explanation	INA				INB			
		CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Read remaining time of the step	Unit: sec	H111E	H121E	H131E	H141E	H151E	H161E	H171E	H181E
Read remaining time of the step	Unit: min	H111F	H121F	H131F	H141F	H151F	H161F	H171F	H181F
Read the NO. of the current pattern	0 ~ 7	H1120	H1220	H1320	H1420	H1520	H1620	H1720	H1820
Read the NO. of the current step	0 ~ 7	H1121	H1221	H1321	H1421	H1521	H1621	H1721	H1821
NO. of start pattern	0 ~ 7	H1122	H1222	H1322	H1422	H1522	H1622	H1722	H1822
NO. of start step	0 ~ 7	H1123	H1223	H1323	H1423	H1523	H1623	H1723	H1823

## • Programmable Parameter Setting

Content	Explanation	Pattern 0	Pattern 1	Pattern 2	Pattern 3	Pattern 4	Pattern 5	Pattern 6	Pattern 7
Max. number of steps in the pattern	0 ~ 7 = N: The pattern executes from step 0 to N.	H2068	H2069	H206A	H206B	H206C	H206D	H206E	H206F
Number of cycles of pattern 0 ~ 7 execution	0 ~ 199: The pattern has been executed for 1 ~ 200 times	H2070	H2071	H2072	H2073	H2074	H2075	H2076	H2077
NO. of current link pattern	0 ~ 8: 8 refers to end of program; 0 ~ 7 refer to the NO. of next pattern	H2078	H2079	H207A	H207B	H207C	H207D	H207E	H207F

Address	Default	Content	Explanation
2000H ~ 203FH	0	Target temperatures for pattern 0 ~ 7 Pattern 0: 2000H ~ 2007H	Unit: 0.1°C
2080H ~ 20BFH	0	Execution time for pattern 0 ~ 7 Pattern 0: 2080H ~ 2087H	Time: 0 ~ 900 (Unit: 1 min)

4. Communication format: H03 = read bit data; H06 = write bit data



• **ASCII Mode**

Read Command		Read Response Message		Write Command		Write Response Message		
Start word	','	Start word	','	Start word	','	Start word	','	
Machine address 1	'0'	Machine address 1	'0'	Machine address 1	'0'	Machine address 1	'0'	
Machine address 0	'1'	Machine address 0	'1'	Machine address 0	'1'	Machine address 0	'1'	
Command 1	'0'	Command 1	'0'	Command 1	'0'	Command 1	'0'	
Command 0	'3'	Command 0	'3'	Command 0	'6'	Command 0	'6'	
Read start address of data/bit	'1'	Length of response data (byte)	'0'	Data address	'1'	Data address	'1'	
	'0'		'4'		'0'		'0'	
	'0'	Data content in H1000	'0'		'0'		'0'	'0'
	'0'		'1'		'1'		'1'	
Read length of data/bit (word/bit)	'0'	Data content in H1001	'F'	Write data content	'0'	Write data content	'0'	
	'0'		'4'		'3'		'3'	
	'0'	Data content in H1001	'0'		'E'		'E'	'E'
	'2'		'0'		'8'		'8'	
LRC1 check	'E'		'0'	LRC1 check	'F'	LRC1 check	'F'	
LRC0 check	'A'		'0'	LRC0 check	'D'	LRC0 check	'D'	
End word 1	CR	LRC1 check	'0'	End word 1	CR	End word 1	CR	
End word 0	LF	LRC0 check	'3'	End word 0	LF	End word 0	LF	
		End word 1	CR					
		End word 0	LF					

• **LRC Check**

Sum up the contents from "machine address" to "data content", e.g. H01 + H03 + H10 + H00 + H00 + H02 = H16. Obtain 2's complement H EA.

• **RTU Mode**

Read Command		Read Response Message		Write Command		Write Response Message	
Machine address	H01	Machine address	H01	Machine address	H01	Machine address	H01
Command	H03	Command	H03	Command	H06	Command	H06
Read start address of data	H10	Length of response data (byte)	H04	Write data address	H10	Write data address	H10
	H00				H01		H01
Read length of data (bit/word)	H00	Data content 1	H01	Write data content	H03	Write data content	H03
	H02		HF4		H20		H20
CRC low byte	HC0	Data content 2	H03	CRC low byte	HDD	CRC low byte	HDD
CRC high byte	HCB		H20	CRC high byte	HE2	CRC high byte	HE2
				CRC low byte	HBB		
			CRC high byte	H15			

**CRC (Cyclical Redundancy Check) is obtained by the following steps:**

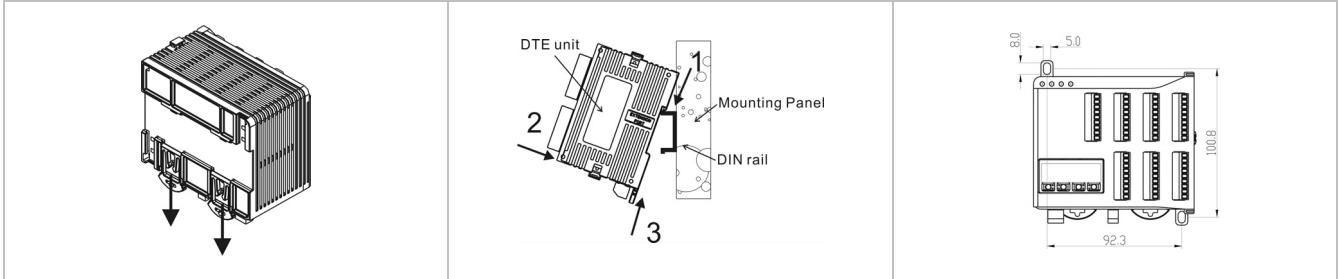
```

unsigned int reg_crc = 0xffff;
i = 0;
while (length--)
{ reg_crc ^= RTUData[i];
  i++;
  for (j = 0; j < 8; j++)
  { if (reg_crc & 0x01) reg_crc = (reg_crc >> 1) ^ 0xA001;
    else reg_crc = reg_crc >> 1;
  }
}
return(reg_crc);

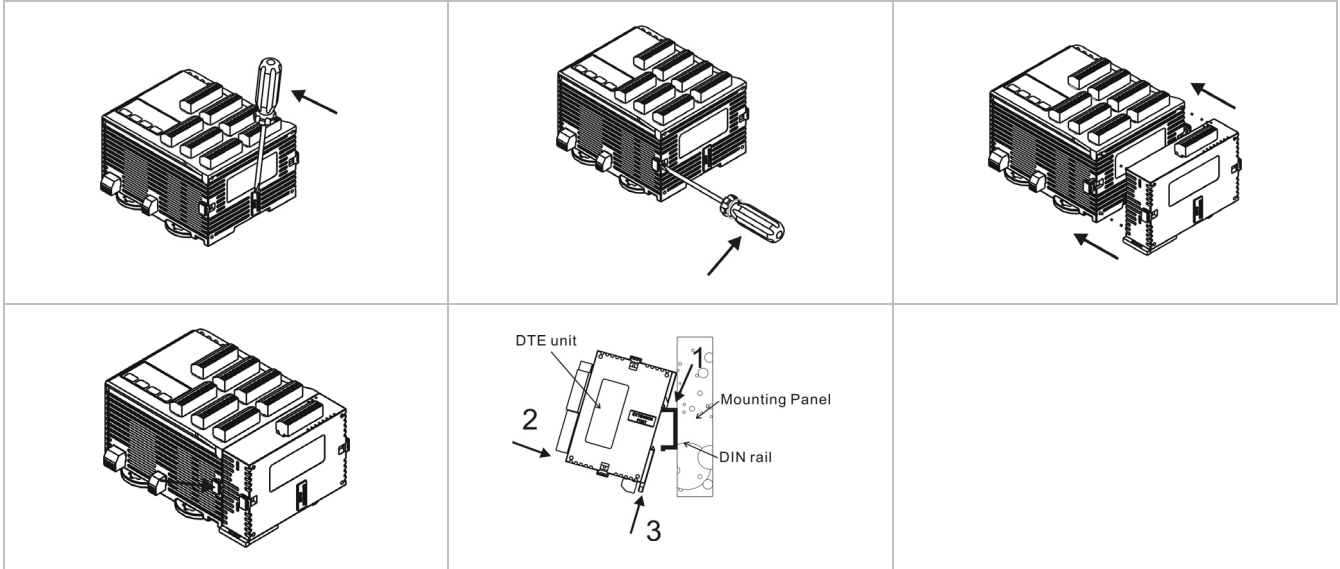
```

**Software for Setting up Communication on PC:** Download the free software on Delta's website.

## ■ How to Mount & DIN Rail Size



Connect maximum 7 DTC2000 or DTC2001 controllers to DTE by using DIN rail.



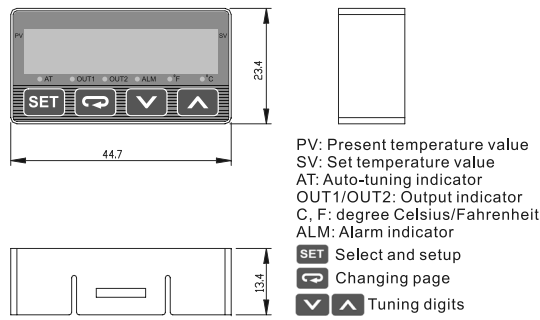
## DTE-2DS DTE Accessory Instruction Sheet

Thank you very much for choosing DTE-2DS. Please read this instruction sheet before using your DTE-2DS to ensure proper operation. Keep this instruction sheet handy for quick reference.

### Warning

1. Please hold the plastic terminal when installing DTE-2DS to prevent electrostatic discharge (ESD).
2. Prevent dust or metallic debris from falling into the device and cause malfunction. **DO NOT** modify or uninstall DTE-2DS without being permitted. **DO NOT** use empty terminals.
3. When installing DTE-2DS, please make sure the power of DTE main unit is switched off and insert DTE-2DS into the correct slot on DTE main unit.
4. Make sure you install DTE-2DS correctly before switching on the power; otherwise serious damage may occur.
5. **DO NOT** touch the terminals or repair the device when the power is on; otherwise an electric shock may occur.

### Product Outline & Dimension



### Electrical Specifications

Input power	DC +5V
Power consumption	Max. 0.5W
Display	Single row 7-segment LED display, two 4 bits PV: red SV: green
Keys	4 keys for selecting, changing pages and tuning
Terminal connection	Can only be inserted into the "Display and Setup Unit" slot on DTE main unit

### Setting up Parameters

**Switching modes:** DTE-2DS is in "operation mode" when the power is switched on, Press **SET** to enter "regulation mode". Press **SET** for more than 3 seconds in the operation mode to enter "initial setting mode". Press **SET** in the regulation mode or initial setting mode to return to the operation mode.

**PV/SV:** Displaying the present value and set value. Use **↓** **↑** to change the set value.

**How to set up:** Use **↔** in the three modes to select the parameter to be set up and **↓** **↑** to modify the settings. Press **SET** to save the setting.

**How to switch modes by keys and set up parameters:**



Regulation Mode	Operation Mode	Initial Setting Mode
<b>PAGE</b> Select channel Press <b>↔</b> ↓	<b>1234</b> Use <b>↓</b> <b>↑</b> to set up target temperature (SV) Press <b>↔</b> ↓	<b>LnPt</b> Set up input type Press <b>↔</b> ↓
<b>At</b> Auto-tuning (Set it up when in PID control and RUN) Press <b>↔</b> ↓	<b>r-S</b> Control loop RUN/STOP Press <b>↔</b> ↓	<b>tPUn</b> Set up temperature unit Press <b>↔</b> ↓

Regulation Mode	Operation Mode	Initial Setting Mode
<b>P</b> PID proportional band (Set it up when in PID control) Press <b>↔</b> ↓	<b>PtRN</b> Set up start pattern (Set it up when in PID control) Press <b>↔</b> ↓	<b>tP-H</b> Set up upper limit of temperature Press <b>↔</b> ↓
<b>t</b> Set up PID Ti value (Set it up when in PID control) Press <b>↔</b> ↓	<b>StEP</b> Set up start step (Set it up when in PID program control) Press <b>↔</b> ↓	<b>tP-L</b> Set up lower limit of temperature Press <b>↔</b> ↓
<b>d</b> Set up PID Td value (Set it up when in PID control) Press <b>↔</b> ↓	<b>SP</b> Set up the position of decimal point ( <b>Not</b> for thermocouple R, S, B type) Press <b>↔</b> ↓	<b>Ctrl</b> Select control mode Press <b>↔</b> ↓
<b>Pdof</b> or <b>CoF</b> Set up PD/PID control offset (When in PID control, set up Pdof when Ti=0. AT sets up ioF automatically when Ti≠0.) Press <b>↔</b> ↓	<b>ALIH</b> or <b>ALAH</b> Without/with group INB Set up upper limit of Alarm 1 Press <b>↔</b> ↓	<b>S-o-1</b> Set up output 1 (Heating, cooling or proportional output) Press <b>↔</b> ↓
<b>tS-1</b> Hysteresis for output 1 (Set it up when in ON/OFF control) Press <b>↔</b> ↓	<b>ALIL</b> or <b>ALAL</b> Without/with group INB Set up lower limit of Alarm 1 Press <b>↔</b> ↓	<b>S-o-2</b> Set up output 2 (Heating, cooling or alarm output) Press <b>↔</b> ↓
<b>tS-2</b> Hysteresis for output 2 (Set it up when in ON/OFF control) Press <b>↔</b> ↓	<b>AL2H</b> Without group INB Set up upper limit of Alarm 2 Press <b>↔</b> ↓	<b>AL1</b> or <b>AL2</b> Without/with group INB Set up Alarm 1 mode Press <b>↔</b> ↓
<b>Pd-1</b> Control cycle for output 1 (Set it up when in PID/programmable PID/manual control) Press <b>↔</b> ↓	<b>AL2L</b> Without group INB Set up lower limit of Alarm 2 Press <b>↔</b> ↓	<b>AL2</b> Without group INB Set up Alarm 2 mode Press <b>↔</b> ↓
<b>Pd-2</b> Control cycle for output 2 (Set it up when in PID/programmable PID/manual control) Press <b>↔</b> ↓	<b>LoC</b> For locking the keys on the panel Press <b>↔</b> ↓	<b>CoPY</b> Set up copy function Press <b>↔</b> ↓
<b>CoEF</b> Ratio of output 1 & output 2 when in dual output control. Pb2 = Pb1 × COEF (Set it up when in PID/programmable PID + dual output) Press <b>↔</b> ↓	<b>out1</b> For displaying and tuning the value of output 1 (Displayed when in PID/programmable PID/manual control RUN) Press <b>↔</b> ↓	<b>C-SL</b> Select ASCII/RTU communication format Press <b>↔</b> ↓
<b>deAd</b> Set up the overlapped area for dual output (dead band) (Set it up when in dual output) Press <b>↔</b> ↓	<b>out2</b> For displaying and tuning the value of output 2 (Displayed when in PID/programmable PID/manual control RUN) Press <b>↔</b> ↓	<b>C-no</b> Set up communication address Press <b>↔</b> ↓
<b>tPof</b> For tuning temperature offset Press <b>↔</b> ↓	Press <b>↔</b> ▷ Return to "target temperature" Press <b>↔</b> ↓	<b>bPS</b> Set up communication baud rate Press <b>↔</b> ↓
<b>onRY</b> Set up upper limit for control output Press <b>↔</b> ↓	Press <b>↔</b> ↓	<b>LEN</b> Set up data length Press <b>↔</b> ↓
<b>onLn</b> Set up lower limit for control output Press <b>↔</b> ↓	Press <b>↔</b> ↓	<b>PrEY</b> Set up parity bit Press <b>↔</b> ↓

Regulation Mode	Operation Mode	Initial Setting Mode
<b>ALAd</b> Set up delay time for alarm output Press <b>↔</b> ↓	Press <b>↔</b> ↓	<b>StoP</b> Set up stop bit Press <b>↔</b> ▷ Return to "set up input type"
<b>CrH</b> For tuning upper limit of analog output (Displayed when in analog output) Press <b>↔</b> ↓	Press <b>↔</b> ↓	Press <b>↔</b> ↓
<b>CrLo</b> For tuning lower limit of analog output (Displayed when in analog output) Press <b>↔</b> ↓	Press <b>↔</b> ↓	Press <b>↔</b> ↓
<b>ProP</b> Set up positive/negative proportional output (Set it up when in proportional output control) Press <b>↔</b> ▷ Return to "auto-tuning"	Press <b>↔</b> ↓	Press <b>↔</b> ↓

### Types of Input Sensors & Temperature Range

1. Set up input sensor: Enter parameter **LnPt** (see "Setting up Parameters" section for details) in "initial setting mode" and select an input sensor (see Table 1).
2. Set up temperature range: Enter parameter **tP-H** and **tP-L** (see "Setting up Parameters" section for details) in "initial setting mode" to set up the temperature range.
3. Set up the position of decimal point: Enter parameter **SP** (see "Setting up Parameters" section for details) in "operation mode". The position of decimal point will change the temperature range. The screen displays only 4 digits; therefore, you have to set "0" in this parameter if you wish to display values bigger than 999 or smaller than -99. The setting will not be saved. Default = 1.

Input Sensor Type	Display	Range
Platinum resistance (Cu50)	<b>Cu50</b>	-50 ~ 150°C
Platinum resistance (Ni120)	<b>n120</b>	-80 ~ 300°C
Platinum resistance (Pt100)	<b>Pt</b>	-200 ~ 850°C
Platinum resistance (JP100)	<b>JPt</b>	-20 ~ 400°C
Thermocouple TXK type	<b>tXt</b>	-200 ~ 800°C
Thermocouple U type	<b>U</b>	-200 ~ 500°C
Thermocouple L type	<b>L</b>	-200 ~ 850°C
Thermocouple B type	<b>b</b>	100 ~ 1,800°C
Thermocouple S type	<b>S</b>	0 ~ 1,700°C
Thermocouple R type	<b>r</b>	0 ~ 1,700°C
Thermocouple N type	<b>n</b>	-200 ~ 1,300°C
Thermocouple E type	<b>E</b>	0 ~ 600°C
Thermocouple T type	<b>t</b>	-200 ~ 400°C
Thermocouple J type	<b>J</b>	-100 ~ 1,200°C
Thermocouple K type	<b>K</b>	-200 ~ 1,300°C

Table 1

### Setting up Control Output

**For PID Control Application:**

1. **Set up 2 outputs:** Enter parameter **S-o-1** and **S-o-2** in "initial setting mode" (see "Setting up Parameters" section for details). Set up one of the two parameters as **HEAt** or **CoOL** of control output.
2. **Set up control type:** Enter parameter **Ctrl** in "initial setting mode" (see "Setting up Parameters" section for details) and set it up as **Pd** (PID) control.
3. **Set up parameters:** In "regulation mode"
  - Parameter **At**: Can be set up when parameter **r-S** is set as **rUn**. When **At** is set as **on**, the program will calculate parameters **P**, **t**, **d**, **CoF** and **CoEF** automatically and save them.
  - Parameter **P**, **t** and **d**.

- Parameter **Pdof** and **Pdof**: **Pdof** can be set up when parameter **0** is set as "0". **Pdof** can be set up when **0** is not "0".
- Parameter **Pd-1** and **Pd-2**: **Pd-1** (control cycle for output 1) can be set up when parameter **S-o-1** is set as **HEAT** (heating) or **COOL** (cooling) output. **Pd-2** (control cycle for output 2) can be set up when parameter **S-o-2** is set as **HEAT** (heating) or **COOL** (cooling) output.
- Parameter **CoEF** and **dERd**: Can be set up when parameter **S-o-1** and **S-o-2** are set as **HEAT** (heating) or **COOL** (cooling) output. (The settings in **S-o-1** and **S-o-2** have to be different.)

#### For ON/OFF Control Application:

- Set up 2 outputs:** Enter parameter **S-o-1** and **S-o-2** in "initial setting mode" (see "Setting up Parameters" section for details). Set up one of the two parameters as **HEAT** or **COOL** of control output.
- Set up control type:** Enter parameter **Ctrl** in "initial setting mode" (see "Setting up Parameters" section for details) and set it up as **onof** (ON/OFF) control.
- Set up parameters:** In "regulation mode"
  - Parameters **tS-1** and **tS-2**: **tS-1** (hysteresis for output 1) can be set up when parameter **S-o-1** is set as **HEAT** (heating) **COOL** (cooling) output. **tS-2** (hysteresis for output 2) can be set up when parameter **S-o-2** is set as **HEAT** (heating) or **COOL** (cooling) output. You can only set up **tS-1** when **S-o-1** and **S-o-2** are set as **HEAT** or **COOL** at the same time.
  - Parameter **dERd**: Can be set up when parameter **S-o-1** and **S-o-2** are set as control output, and the settings in **S-o-1** and **S-o-2** are different, e.g. output 1 is **HEAT** (heating), and output 2 is **COOL** (cooling).

#### For Manual Control Application:

- Set up 2 outputs:** Enter parameter **S-o-1** and **S-o-2** in "initial setting mode" (see "Setting up Parameters" section for details). Set up one of the two parameters as **HEAT** or **COOL** of control output.
- Set up control type:** Enter parameter **Ctrl** in "initial setting mode" (see "Setting up Parameters" section for details) and set it up as **manu** (manual) control.
- Set up parameters:** In "regulation mode"
  - Parameter **Pd-1** and **Pd-2**: **Pd-1** (control cycle for output 1) can be set up when parameter **S-o-1** is set as **HEAT** (heating) or **COOL** (cooling) output. **Pd-2** (control cycle for output 2) can be set up when parameter **S-o-2** is set as **HEAT** (heating) or **COOL** (cooling) output.
  - Parameter **out-1** and **out-2** (in "operation mode"): **out-1** can be set up when parameter **S-o-1** is set as **HEAT** (heating) or **COOL** (cooling) output. **out-2** can be set up when parameter **S-o-2** is set as **HEAT** (heating) or **COOL** (cooling) output.

#### For Programmable PID Application:

- Set up 2 outputs:** Enter parameter **S-o-1** and **S-o-2** in "initial setting mode" (see "Setting up Parameters" section for details). Set up one of the two parameters as **HEAT** or **COOL** of control output.
- Set up control type:** Enter parameter **Ctrl** in "initial setting mode" (see "Setting up Parameters" section for details) and set it up as **prog** (programmable) control.
- Set up parameters:** In "regulation mode"
  - Parameter **P**, **I** and **d**.
  - Parameter **Pdof**: **Pdof** can be set up when parameter **0** is set as "0".
  - Parameter **Pd-1** and **Pd-2**: **Pd-1** (control cycle for output 1) can be set up when parameter **S-o-1** is set as **HEAT** (heating) or **COOL** (cooling) output. **Pd-2** (control cycle for output 2) can be set up when parameter **S-o-2** is set as **HEAT** (heating) or **COOL** (cooling) output.
  - Parameter **CoEF** and **dERd**: Can be set up when parameter **S-o-1** and **S-o-2** are set as **HEAT** (heating) or **COOL** (cooling) output. (The settings in **S-o-1** and **S-o-2** have to be different.)
  - Parameter **Ptcrn** and **StEP** (in "operation mode"): Can be set up when parameter **r-S** is set as **StoP** or **PStEP**.

#### For Proportional Output Application:

- Set up output function:** Enter parameter **S-o-1** in "initial setting mode" (see "Setting up Parameters" section for details) and set it as **prop** (proportional) output.
- Set up parameters:** In "regulation mode"
  - Parameter **prop**

#### For Upper/Lower Limits of Control Output:

- Set up upper limit:** Enter parameter **onRY** in "regulation mode" (see "Setting up Parameters" section for details). Range: Lower limit ~ 100%.
- Set up lower limit:** Enter parameter **onLn** in "regulation mode" (see "Setting up Parameters" section for details). Range: 0 ~ upper limit %.

#### For Alarm Application:

- Set up output function (only when there is group INB):** Enter parameter **S-o-2** in "initial setting

- mode" (see "Setting up Parameters" section for details) and set it as **ALAN** (alarm) output.
- Set up alarm type:** Enter parameter **ALAN** (with INB) or **ALAI** and **ALAR2** (without INB) in "initial setting mode". See Table 2 for more details on the alarm output.
- Set up parameters:** In "operation mode"
  - Parameter **ALAH** and **ALAL**: Can be set up when there is group INB.
  - Parameter **ALIH**, **ALIL**, **AL2H** and **AL2L**: Can be set up when there is no group INB.
- Set up delay alarm output:** Enter parameter **ALnd** in "regulation mode" (unit: second). The alarm will be enabled only when the temperature reaches the alarm output condition, and the condition remains until the delay time is reached.

DTE main unit offers 2 groups of alarm output, each with 12 alarm modes in the initial setting mode. When SV is higher or lower than SV, the alarm output will be enabled. See the table in the next column for the explanations on the 12 alarm output modes.

*Note: AL-H and AL-L include AL1H, AL2H and AL1L, AL2L.*

SV	Alarm Mode	Alarm Output Operation
0	No alarm	OFF
1	Alarm output is enabled when the temperature reaches upper and lower limits: The alarm will be enabled when PV exceeds SV + AL-H or falls below SV - AL-L.	ON OFF 
2	Alarm output will be enabled when the temperature reaches the upper limit: The alarm will be enabled when PV exceeds SV + AL-H.	ON OFF 
3	Alarm output will be enabled when the temperature reaches the lower limit: The alarm will be enabled when PV falls below SV - AL-L.	ON OFF 
4	Alarm output will be enabled when PV is between SV + AL-H and SV - AL-L.	ON OFF 
5	Alarm output will be enabled when the temperature reaches the absolute value of the upper and lower limits: The alarm will be enabled when PV exceeds AL-H or falls below AL-L.	ON OFF 
6	Alarm output will be enabled when the temperature reaches the absolute value of the upper limit: The alarm will be enabled when PV exceeds AL-H.	ON OFF 
7	Alarm output will be enabled when the temperature reaches the absolute value of the lower limit: The alarm will be enabled when PV falls below AL-L.	ON OFF 
8	Upper/lower limit standby alarm: The alarm will be enabled when PV reaches SV and further exceeds SV + AL-H or falls below SV - AL-L.	ON OFF 
9	Upper limit standby alarm: The alarm will be enabled when PV reaches SV and further exceeds SV + AL-H.	ON OFF 
10	Lower limit standby alarm: The alarm will be enabled when PV reaches SV and further falls below SV - AL-L.	ON OFF 
11	Upper limit hysteresis alarm: The alarm will be enabled when PV exceeds SV + AL-H. The alarm will be disabled when PV falls below SV.	ON OFF 
12	Lower limit hysteresis alarm: The alarm will be enabled when PV falls below SV - AL-L. The alarm will be disabled when PV exceeds SV.	ON OFF 

Table 2

## Setting up Communication

- Set up communication:** Enter parameter **C-SL**, **C-no**, **bPS**, **LEN**, **PrEY** and **StoP** in "initial setting mode" (see "Setting up Parameters" section for details) and select your desired communication settings.
- DTE series temperature controller is able to set up or read communication settings through DTE-2DS.

## Selecting Channel

- Select channel:** Enter parameter **PRGE** in "regulation mode" (see "Setting up Parameters" section for details) and select the channel to be monitored.
- How does it work:** DTE main unit has maximum 8 channels which can be connected to 8 input sensors at the same time. The 8 input channels belong to group INA and INB, each group with 4 input channels. INB is optional accessory; therefore if INB is not inserted in DTE, DTE will only show 4 channels.

## Setting up Copy Function

- Set up the function:** Enter parameter **CoPY** in "initial setting mode" (see "Setting up Parameters"

section for details) and select the function you desire.

- How does it work:** The copy function allows a DTE main unit to copy its parameters (including the values set in the parameter and communication settings) to another DTE main unit through DTE-2DS. Follow the steps below:
  - Insert DTE-2DS into the DTE main unit to be copied. Enter parameter **CoPY** in "initial setting mode" and select **rERd**, and DTE-2DS will read the parameters in the DTE main unit. Next, you will see **Good** on the screen, indicating that the copy is successful. **FAIL** indicates the copy fails. Press **▲** to return to "operation mode" and you will see the present temperature value (PV) and set temperature value (SV).
  - Switch off DTE and withdraw DTE-2DS. Insert DTE-2DS into another DTE main unit. Enter parameter **CoPY** in "initial setting mode" and select **WrTE**. DTE-2DS will write the parameters into it. Next, you will see **Good** on the screen, indicating that the writing-in is successful. **FAIL** indicates the writing-in fails. Press **▲** to return to "operation mode" and you will see the present temperature value (PV) and set temperature value (SV).

## Locking the Keys on Panel

- Lock the keys:** Enter parameter **LoC** in "operation mode" (see "Setting up Parameters" section for details) and select the function you desire.
- How does it work:** **LoC1** indicates locking all the keys on the panel. **LoC2** indicates that you can only modify the set temperature value (SV), and all other functions are locked.
- Press **SET** and **↺** at the same time to unlock the keys.

## Analog Output & Temperature Tuning

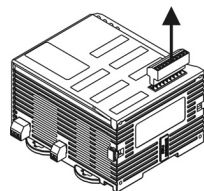
- Set up analog output tuning:** Enter parameter **CRH** and **CRLo** in "regulation mode" (see "Setting up Parameters" section for details) and tune the parameter to the desired output value.
- Temperature offset tuning:** Enter parameter **tPoF** in "regulation mode" and tune the parameter to the displayed temperature value.
- How does it work:**
  - Tuning analog output: For example, if you would like to have accurate 4 ~ 20mA of output, you can set up output 0% by manual control, connect the output to ampere meter and tune parameter **CRLo** making the meter point to 4mA. Next, set up output 100% by manual control and tune parameter **CRH** making the meter point to 20mA.
  - Tuning temperature offset: This allows the displayed temperature to plus or minus 1 offset value.

## Error Message

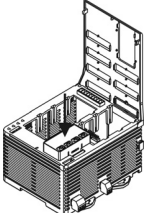
Error	PV	SV
Input sensor not connected	<b>no</b>	<b>Cont</b>
Internal communication error	<b>LnCo</b>	<b>FAIL</b>
Output error	<b>Err</b>	<b>out</b>
Input error	<b>Err</b>	<b>LnPE</b>
Storage error	<b>Err</b>	<b>PrOn</b>
Channel disabled	<b>dCS</b>	<b>PRGE</b>
Channel being initialized	<b>dTE</b>	<b>LnCt</b>

## How to Install

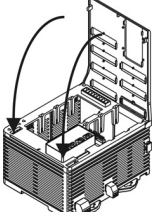
① Remove all the terminal blocks on the panel.



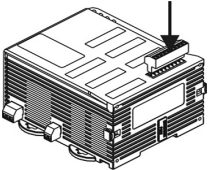
② Uncover the panel and insert DTE-2DS to the "operation interface" slot.



③ Cover up the panel.



④ Insert the terminal blocks back to their positions.



DTE Accessories

Instruction Sheet

Thank you very much for choosing DTE series accessory. Please read this instruction sheet before using your accessory to ensure proper operation. Keep this instruction sheet handy for quick reference.

Warning

1. Please hold the plastic terminal when installing the accessory to prevent electrostatic discharge (ESD).
2. Prevent dust or metallic debris from falling into the device and cause malfunction. DO NOT modify or uninstall the accessory without being permitted. DO NOT use empty terminals.
3. When installing the accessory, please make sure that the power of DTE main unit is switched off and insert the accessory into the correct slot on DTE main unit.
4. Make sure you install the accessory correctly before switching on the power; otherwise serious damage may occur.
5. DO NOT touch the terminals or repair the device when the power is on; otherwise an electric shock may occur.

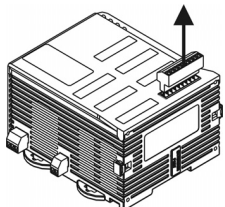
Functions & Electrical Specifications

Power consumption	Max. 1.3W
Output accessories	<ul style="list-style-type: none"> <li>■ <b>DTE20R</b>: 4 channels of relay output, SPST, max. AC 250V load, 3A resistive load</li> <li>■ <b>DTE20V</b>: 4 channels of voltage pulse output, DC 24V, max. 40mA current output</li> <li>■ <b>DTE20C</b>: 4 channels of current output, DC 4 ~ 20mA output (resistive load &lt; 500Ω)</li> <li>■ <b>DTE20L</b>: 4 channels of analog voltage output 0 ~ 10V (resistive load &gt; 1,000Ω)</li> </ul>
Input accessories	<ul style="list-style-type: none"> <li>■ <b>DTE2CT</b>: 4 channels of current transformer (CT) input. CT range: 0.5 ~ 30A Resolution: 0.1A; Offset: ±0.5A</li> <li>■ <b>DTE20D</b>: 8 channels of EVENT input. The short circuit resistance of the channel has to be smaller than 1kΩ; the open circuit resistance has to be bigger than 100kΩ.</li> </ul>
Terminal connection	<ul style="list-style-type: none"> <li>■ Current output and analog voltage output boards can only be inserted into main output slots (OUT1, OUT2) on DTE main unit.</li> <li>■ Relay output and voltage output boards can only be inserted into main output slots (OUT1, OUT2) and sub-output slots (SUB1, SUB2)</li> <li>■ CT input and EVENT input boards can only be inserted into the auxiliary slot (AUX) on DTE main unit.</li> </ul>

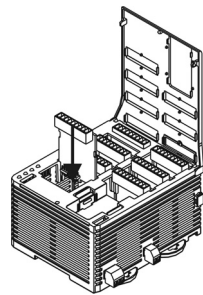
The accessories using for the DTE main unit, please download the DTE10P and DTE10T main unit operating manual for reference on Delta website.

How to Install

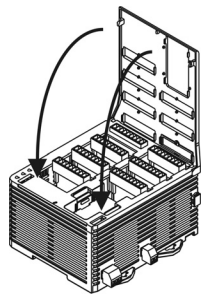
① Remove all the terminal blocks on the panel.



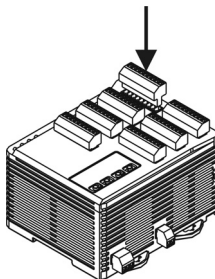
② Uncover the panel. Make sure which slot is the correct one and insert the accessory into the slot.



③ Cover up the panel.



④ Insert the terminal blocks back.



非常感謝您選用台達產品，請在使用前，詳細閱讀本使用說明書，並將手冊放置於易拿處以便參考。

注意事項

1. 安裝時，請握住塑膠端子部分，防止靜電破壞(ESD)。
2. 如果有塵土或金屬殘渣掉入機身，可能會造成誤運行。請勿修改或擅自拆卸電路板。空餘端子請勿使用。
3. 安裝配件電路板時，請先確認主機已斷電，並確認該配件正確的插槽位置。
4. 上電前請確認裝配是否正確及配件電路板到定位，否則可能造成嚴重損壞。
5. 上電時請勿接觸機體端子或進行維修，否則可能遭致電擊。

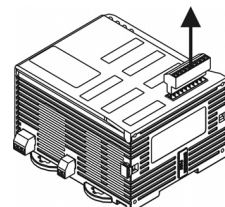
功能與電氣規格

電源消耗功率	Max. 1.3W
輸出配件種類	<ul style="list-style-type: none"> <li>■ <b>DTE20R</b> : 4 通道繼電器輸出，單刀單閘，最大負載為交流 250 伏特，3 安培的電阻性負載。</li> <li>■ <b>DTE20V</b> : 4 通道電壓脈衝輸出，直流 24 伏特，最大輸出電流 40 毫安培。</li> <li>■ <b>DTE20C</b> : 4 通道電流輸出，直流 4 ~ 20 毫安培輸出（負載阻抗需小於 500 歐姆）。</li> <li>■ <b>DTE20L</b> : 4 通道類比電壓輸出 0 ~ 10V（負載阻抗需大於 1,000 歐姆）。</li> </ul>
輸入配件種類	<ul style="list-style-type: none"> <li>■ <b>DTE2CT</b> : 4 通道電流檢測輸入，電流檢測範圍 0.5A~30 安培，解析度 0.1 安培，誤差±0.5 安培。</li> <li>■ <b>DTE20D</b> : 8 通道 EVENT 輸入，通道短路電阻必須小於 1k 歐姆，開路電阻必須大於 100k 歐姆。</li> </ul>
端子連接功能	<ul style="list-style-type: none"> <li>■ 電流輸出及類比電壓輸出板僅可插入主機的主輸出 (OUT1、OUT2) 插槽</li> <li>■ 繼電器輸出及電壓脈衝輸出板可插入主輸出插槽 (OUT1、OUT2) 及次輸出 (SUB1、SUB2) 插槽</li> <li>■ 電流檢測輸入及 EVENT 輸入板僅可插入主機的輔助 (AUX) 插槽</li> </ul>

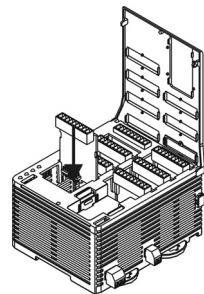
本配件為配合 DTE 主機使用，請於台達網站下載 DTE10P 及 DTE10T 主機操作手冊參考使用。

安裝方式及步驟

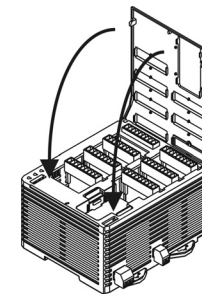
① 移除面板上所有脫落式端子



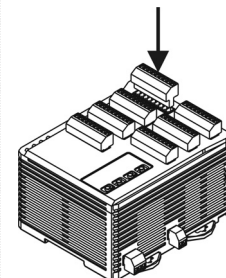
② 掀開面板，確認該配件正確的插槽位置，插入電路板至定位。



③ 蓋回面板至定位



④ 裝回脫落式端子至定位



非常感谢您选用台达产品，请在使用前，详细阅读本使用说明书，并将手册放置于易拿处以便参考。

## ■ 注意事項

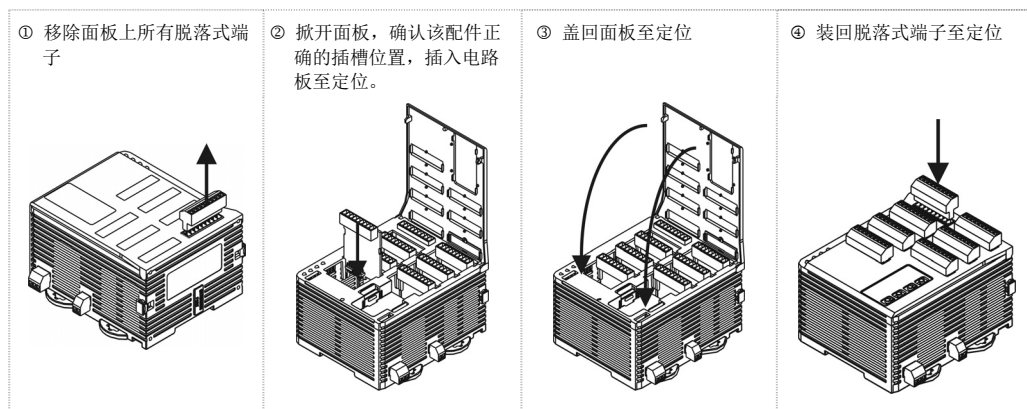
1. 安装时，请握住塑胶端子部分，防止静电破坏 (ESD)。
2. 如果有尘土或金属残渣掉入机身，可能会造成误运行。请勿修改或擅自拆卸电路板。空余端子请勿使用。
3. 安装配件电路板时，请先确认主机已断电，并确认该配件正确的插槽位置。
4. 上电前请确认装配是否正确及配件电路板到定位，否则可能造成严重损坏。
5. 上电时请勿接触机体端子或进行维修，否则可能遭致电击。

## ■ 功能與電氣規格

电源消耗功率	Max. 1.3W
输出配件种类	<ul style="list-style-type: none"> <li>■ <b>DTE20R</b>: 4 通道继电器输出，单刀单闸，最大负载为交流 250 伏特，3 安培的电阻性负载。</li> <li>■ <b>DTE20V</b>: 4 通道电压脉冲输出，直流 24 伏特，最大输出电流 40 毫安培。</li> <li>■ <b>DTE20C</b>: 4 通道电流输出，直流 4 ~ 20 毫安培输出（负载阻抗需小于 500 欧姆）。</li> <li>■ <b>DTE20L</b>: 4 通道模拟电压输出 0 ~ 10V（负载阻抗需大于 1000 欧姆）。</li> </ul>
输入配件种类	<ul style="list-style-type: none"> <li>■ <b>DTE2CT</b>: 4 通道电流检测输入，电流检测范围 0.5A~30 安培，分辨率 0.1 安培，误差±0.5 安培。</li> <li>■ <b>DTE20D</b>: 8 通道 EVENT 输入，通道短路电阻必须小于 1k 欧姆，开路电阻必须大于 100k 欧姆。</li> </ul>
端子连接功能	<ul style="list-style-type: none"> <li>■ 电流输出及模拟电压输出板仅可插入主机的主输出 (OUT1、OUT2) 插槽</li> <li>■ 继电器输出及电压脉冲输出板可插入主输出插槽 (OUT1、OUT2) 及次输出 (SUB1、SUB2) 插槽</li> <li>■ 电流检测输入及 EVENT 输入板仅可插入主机的辅助 (AUX) 插槽</li> </ul>

✍ 本配件为配合 DTE 主机使用，请于台达网站下载 DTE10P 及 DTE10T 主机操作手册参考使用。

## ■ 安裝方式及步驟



# DTE20T/20P DTE Accessory Instruction Sheet

Thank you very much for choosing DTE20T/20P. Please read this instruction sheet before using your DTE20T/20P to ensure proper operation. Keep this instruction sheet handy for quick reference.

## Warning

1. Please hold the plastic terminal when installing DTE20T/20P to prevent electrostatic discharge (ESD).
2. Prevent dust or metallic debris from falling into the device and cause malfunction. DO NOT modify or uninstall DTE20T/20P without being permitted. DO NOT use empty terminals.
3. When installing DTE20T/20P, please make sure the power of DTE main unit is switched off and insert DTE20T/20P into the correct slot on DTE main unit.
4. Make sure you install DTE20T/20P correctly before switching on the power; otherwise serious damage may occur.
5. DO NOT touch the terminals or repair the device when the power is on; otherwise an electric shock may occur.

## Functions & Electrical Specifications

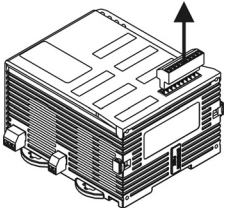
Power consumption	Max. 0.5W
Input sensor	DTE20T (4 channels of thermocouple: K, J, T, E, N, R, S, B, L, U, TXK) DTE20P (3 channels of platinum RTD): Pt100, JPt100, Ni120, Cu50
Sampling cycle	Thermocouple or platinum RTD: 1.0 second (all inputs)
Terminal connection	Can only be inserted into <b>INB</b> slot on DTE10T or DTE10P main unit

The sensor slot (INA/INB) only accepts the same input type. For example, if you select DTE20T as accessory, you can only use it on DTE10T main unit. If you select DTE20P as accessory, you can only use it on DTE10P main unit.

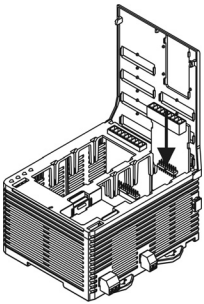
The accessories using for the DTE main unit, please download the DTE10P and DTE10T main unit operating manual for reference on Delta website.

## How to Install

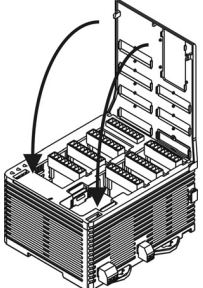
① Remove all the terminal blocks on the panel.



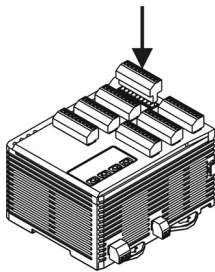
② Uncover the panel. Make sure which slot is the correct one and insert DTE-20T/20P into the slot.



③ Cover up the panel.



④ Insert the terminal blocks back.



# DTE20T/20P 配件安裝手冊

非常感謝您選用台達產品，請在使用前，詳細閱讀本使用說明書，並將手冊放置於易拿處以便參考。

## 注意事項

1. 安裝時，請握住塑膠端子部分，防止靜電破壞(ESD)。
2. 如果有塵土或金屬殘渣掉入機身，可能會造成誤運行。請勿修改或擅自拆卸電路板。空餘端子請勿使用。
3. 安裝配件電路板時，請先確認主機已斷電，並確認該配件正確的插槽位置。
4. 上電前請確認裝配是否正確及配件電路板到定位，否則可能造成嚴重損壞。
5. 上電時請勿接觸機體端子或進行維修，否則可能遭致電擊。

## 功能與電氣規格

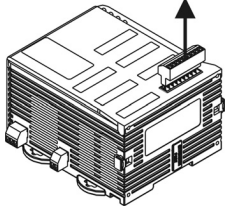
電源消耗功率	Max. 0.5W
輸入感測器	DTE20T (4 通道熱電偶對): K, J, T, E, N, R, S, B, L, U, TXK DTE20P (3 通道白金測溫電阻): Pt100, JPt100, Ni120, Cu50
取樣頻率	熱電偶對或白金測溫電阻: 1.0 秒 (所有輸入)
端子連接功能	僅可插入 DTE10T 或 DTE10P 主機的 <b>INB</b> 插槽

感測器插槽(INA/INB)只能接受相同的輸入形式，例如若配件選擇為 DTE20T，則只能與主機 DTE10T 搭配使用。配件選擇為 DTE20P，則只能與主機 DTE10P 搭配使用。

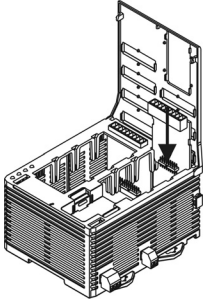
本配件為配合 DTE 主機使用，請於台達網站下載 DTE10P 及 DTE10T 主機操作手冊參考使用。

## 安裝方式及步驟

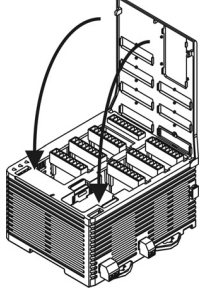
① 移除面板上所有脫落式端子



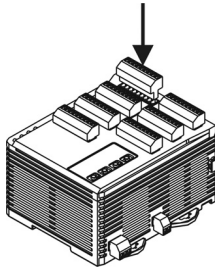
② 掀開面板，確認該配件正確的插槽位置，插入電路板至定位。



③ 蓋回面板至定位



④ 裝回脫落式端子至定位



# DTE20T/20P 配件安裝手冊

非常感谢您选用台达产品，请在使用前，详细阅读本使用说明书，并将手册放置于易拿处以便参考。

## ■ 注意事項

1. 安装时，请握住塑胶端子部分，防止静电破坏 (ESD)。
2. 如果有尘土或金属残渣掉入机身，可能会造成误运行。请勿修改或擅自拆卸电路板。空余端子请勿使用。
3. 安装配件电路板时，请先确认主机已断电，并确认该配件正确的插槽位置。
4. 上电前请确认装配是否正确及配件电路板到定位，否则可能造成严重损坏。
5. 上电时请勿接触机体端子或进行维修，否则可能遭致电击。

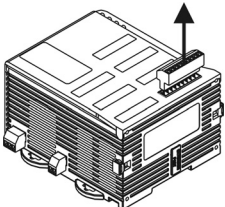
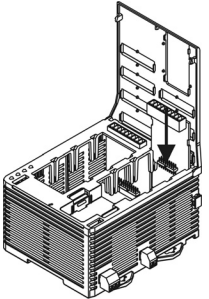
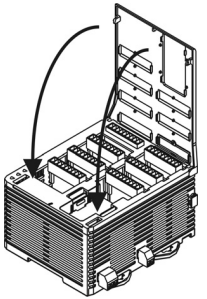
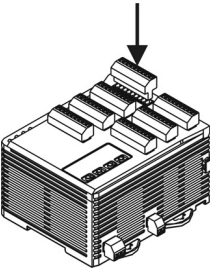
## ■ 功能与電氣規格

电源消耗功率	Max. 0.5W
输入传感器	DTE20T (4 通道热电偶对): K, J, T, E, N, R, S, B, L, U, TXK DTE20P (3 通道白金测温电阻): Pt100, JPt100, Ni120, Cu50
采样频率	热电偶对或白金测温电阻: 1.0 秒 (所有输入)
端子连接功能	仅可插入 DTE10T 或 DTE10P 主机的 <b>INB</b> 插槽

✍ 传感器插槽(INA/INB)只能接受相同的输入形式，例如若配件选择为 DTE20T，则只能与主机 DTE10T 搭配使用。配件选择为 DTE20P，则只能与主机 DTE10P 搭配使用。

✍ 本配件为配合 DTE 主机使用，请于台达网站下载 DTE10P 及 DTE10T 主机操作手册参考使用。

## ■ 安裝方式及步驟

<p>① 移除面板上所有脱落式端子</p> 	<p>② 掀开面板，确认该配件正确的插槽位置，插入电路板至定位。</p> 	<p>③ 盖回面板至定位</p> 	<p>④ 装回脱落式端子至定位</p> 
--	--	--	--